Annex-3(A)

Guidelines for furnishing information for RMS (generic) modelling of Coal fired generation

The guidelines provide the desired information for collection of data for RMS modelling (generic) of coal fired thermal generation

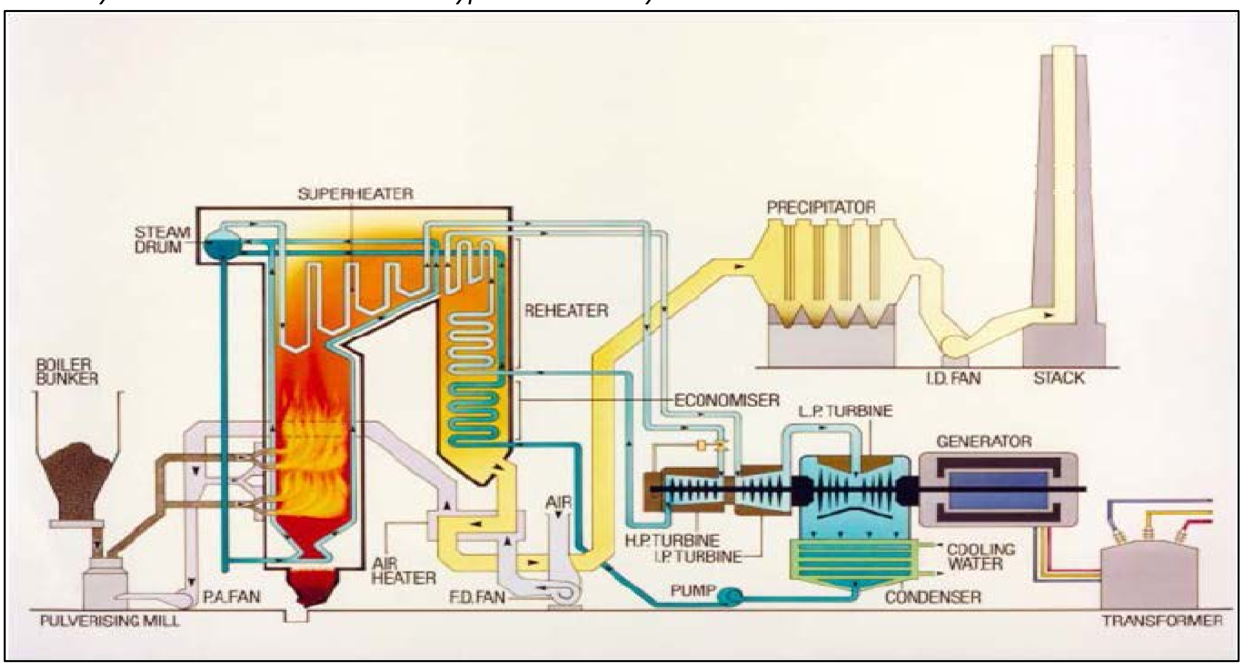
1.0 Coal fired thermal generation technologies:

Coal fired power plants typically burn coal to heat a boiler that produces high-temperature, high-pressure steam that is passed through the turbine to produce mechanical energy (IEEE Power and Energy Society, 2013).

The majority of commercially available coal fired thermal generators use one of the three technologies depending upon the stream pressure within the boiler as listed below:

Technology	Temperature	Pressure
Sub-critical	537 °C / 565 °C	Below 225 kg/cm2
Super-critical	538/565 °C ~ Older units 565/593 °C ~ later commissioned	247kg/cm2
Ultra-supercritical	600/610 °C to 700°C	250-300/cm2

**Figures taken from Standard Technical features of BTG system for subcritical and supercritical units issued by CEA 2013. Above values are typical values only.*



Schematic of a Typical Coal Fired Generator

For Grid-India to have access to verified fit-for-purpose generic RMS models of coal fired thermal generation connected to Indian grid, following information is required:

1. Electrical Single Line Diagram of coal fired thermal station depicting;
   - **For individual generating units:** type of technology, **Complete Generator OEM Technical Datasheet** (which comprises namely generator parameters like impedances & time constants, generator capability curve, V-curve, generator open and short circuit characteristics, excitation system details, inertia of generator & exciter), generator name plate, generator SAT reports including Short circuit and open circuit test results during commissioning/recent overhauling.
   - **Generator step up transformer**: GT name plate/datasheet, details of LV, MV and HV, MVA rating, impedance, tap changer details, vector group, short-circuit parameters (actual positive &

zero sequence impedance of GT, NGR nameplate with impedance).

- **Excitation system: -** Type of excitation system (Direct Current Commutator Exciters (type DC), AC Excitation (Rotor or brushless excitation) Systems (type AC) and Static Excitation Systems (type ST), Excitation system schematics (Block diagram of AVR system), transfer function block diagram of Excitation system, excitation transformer nameplate, saturation curves of the exciter (I_a versus I_f curve), IEEE standard model of excitation system, IEEE standard model and its parameter of subsystems such as Power system stabilizer (PSS), Under Excitation Limiter (UEL), Over Excitation Limiter (OEL), Voltage per Hz Limiter(V/Hz) control etc. and details thereof, factory acceptance test reports (FAT). Excitation system actual settings to be provided. AVR test report (excitation step response test).
- **Power System Stabilizer (PSS):** Transfer function block diagram of PSS, IEEE Standard Model, Actual PSS software settings, PSS commissioning report and **Recent PSS tuning report**.
- **Turbine-Governor system :** Type of turbine (Tandem/Cross compound), model of turbine and boiler (including details of boiler controls, technology, valves, valve characteristics), model of speed governor and turbine load (if applicable) control system (including details of technology, valves, valves characteristics) , mode of operation and control, ramp rates, **turbine inertia**, IEEE standard model of turbine governor system and its transfer function Block diagram and its parameters, details of control mode (boiler-follow, turbine-follow, or coordinated control), commissioning report of turbine-governor system or recent governor testing report.

3.1 Details of models in PSS/E for modelling coal fired thermal generation:

(a) Synchronous Machine

Category	Parameter Description	Data
Generator Nameplate	Rated apparent power in MVA	
	Rated terminal voltage	
	Rated power factor	
	Rated frequency (in Hz)	
	Rated speed (in RPM)	
	Rated excitation (in Amperes and Volts)	
Type of synchronous machine	Round rotor or salient pole No. of Poles:	
Generator capability curve	The generator capability curve shows the reactive capability of the machine and should include any restrictions on the real or reactive power range like under/over excitation limits, stability limits, etc. Capability curve should have properly labelled axis and legible data	
Generator Open Circuit and Short Circuit Characteristic	Graph of excitation current versus terminal voltage and stator current	
	No load excitation current	
	Excitation current at rated stator current	
Generator vee-curves	Otherwise referred to as "V-curve". A plot of the terminal (armature) current versus the generating unit field voltage.	
Resistance values	Resistance measurements of field winding and stator winding to a known temperature	
	Direct axis synchronous reactance Xd in p.u. (Unsaturated or saturated)	
	Direct axis transient synchronous reactance Xd' in p.u. (Unsaturated or saturated)	
	Direct axis sub-transient synchronous reactance Xd'' in p.u. (Unsaturated or saturated)	
	Stator leakage reactance Xa in p.u. (Unsaturated or saturated)	
	Quadrature axis synchronous reactance Xq in p.u. (Unsaturated or saturated)	
	Quadrature axis transient synchronous reactance Xq' in p.u. (Unsaturated or saturated)	

Generator Data sheet	Quadrature axis sub-transient synchronous reactance Xq'' in p.u. (Unsaturated or saturated)	
	Direct axis open circuit transient time constant Tdo' in sec	
	Direct axis open circuit sub-transient time constant Tdo'' in sec	
	Quadrature axis open circuit transient time constant Tqo' in sec	
	Quadrature axis open circuit sub-transient time constant Tqo'' in sec	
	Inertia constant of total rotating mass (generator, AVR, turbo-governor set) H in MW. s/MVA	
	Speed Damping D	
	Saturation constant S (1.0) in p.u.	
	Saturation constant S (1.2) in p.u.	

Category	Parameter Description	Data
Generator step up transformer (GSUT)	Nameplate Rating - Rated primary and secondary voltage - Vector group - Impedance - Tap changer details (Number of taps, tap position, tap ratio etc.)	

(b) Site Load

	Low Output			High Output		
	kW	kvar	kVA	kW	kvar	kVA
Auxiliary Load						

(c) Excitation System

Category	Parameter Description	Data
Type of Automatic Voltage Regulator (AVR)	Manufacturer and product details	
	Type of control system: - Analogue or digital	
	Year of commissioning / Year of manufacture	
	As found settings (obtained either from HMI or downloaded from controller in digital systems)	
Type of excitation system	Static excitation system OR	
	Indirect excitation system (i.e. rotating exciter) - AC exciter, or - DC exciter	
Details of AVR converter	Rated excitation current (converter rating in Amperes)	
	Six pulse thyristor bridge or PWM converter	
Source of excitation supply	Excitation transformer or auxiliary supply (Details thereof)	
	If excitation transformer, nameplate information such as type of transformer, HV and HV winding ratings, positive and zero sequence impedance, tap positions, voltage step per tap is required.	
Schematics	Saturation curves of the exciter (if applicable – see Type AC and DC)	
	Drawings of excitation system, typically prepared and supplied by the OEM	
	Single line diagram (i.e. one-line diagram) for the excitation system	
Excitation limiters	What excitation limiters are commissioned?	
	Under Excitation Limiters settings	
	Over Excitation Limiters settings	
	Voltage/frequency limiter	
	Stator current limiter	
	Minimum excitation current limiter	
PSS	Is the AVR equipped with a PSS?	
	How many input Channels does the PSS have? (speed, real power output or both	

Category	Parameter Description	Data
	If the PSS uses speed, is this a derived speed signal (i.e. synthesized speed signal) or measured directly (i.e. actual rotor speed)?	
	Type of PSS Block Diagram of PSS and as commissioned parameters value (Gain, time constants, filter coefficients, output limits of the PSS)	

(d) Turbine Details

Category	Parameter Description	Data
Manufacturer of turbine	Manufacturer and name plate details Rating of turbine	
Type of Governor	Electro-mechanical governor	
	Digital electric governor	
	Block diagram of the speed governor	
Ramp rates	How fast can the turbine increase and/or decrease load, specified in MW/min	
	Stroke limits of speed changer (values of full stroke, full load and no-load in mm)	
Droop	Droop setting (% on machine base)	
	Frequency influence limiters - Maximum frequency deviation limiter (eg +/-2 Hz) - Maximum influence limiter (eg 10% of rating)	
Dead band	Details of frequency dead band (typically in Hz)	
Steam turbine	**Tandem compound:** all sections on one shaft with a single generator	
	Cross compound: consists of two shafts, each connected to a generator and driven by one or more turbine section	
	Turbine sections: High pressure (HP), intermediate pressure (IP) and low pressure (LP)	
	Reheat or non-reheat: In a reheat, steam upon leaving HP section returns to boiler where it passed through reheater before entering IP section	
	Valves: - Main inlet stop valve (MSV) - Governor control valve (CV) - Reheater stop valve (RSV) - Intercept valves (IV)	
	Turbine control action: - Boiler follow mode - Turbine follow mode - Coordinated control	
	Fast valving /bypass operation	
	Block diagram of the turbine load control	
	Reheater volume (m^3), volume flow (kg/s), and average specific volume (m^3/kg)	

3.2 Generic Models for synchronous machine

There are two typical groups of synchronous machine models, depending upon the type of machine:

- Round rotor machine (2 poles):
  - GENROU – Round rotor machine model with quadratic saturation function
  - GENROE – Round rotor machine model with exponential saturation function
- Salient pole machine (more than two poles):
  - GENSAL – Salient pole machine with quadratic saturation function
  - GENSAE – Salient pole machine with exponential saturation function

Category	Parameter Description	Data
	GENERATOR model	
GENROU OR **GENROE**	Direct axis open circuit transient time constant Tdo' in sec	
	Direct axis open circuit sub-transient time constant Tdo'' in sec	
	Quadrature axis open circuit transient time constant Tqo' in sec	
	Quadrature axis open circuit sub-transient time constant Tqo'' in sec	
	Inertia constant of total rotating mass H in MW. s/MVA	
	Speed Damping D	
	Direct axis synchronous reactance Xd in p.u. (Unsaturated or saturated)	
	Quadrature axis synchronous reactance Xq in p.u. (Unsaturated or saturated)	
	Direct axis transient synchronous reactance Xd' in p.u. (Unsaturated or saturated)	
	Quadrature axis transient synchronous reactance Xq' in p.u. (Unsaturated or saturated)	
	Direct axis sub-transient synchronous reactance Xd'' in p.u. (Unsaturated or saturated) = Quadrature axis sub-transient synchronous reactance Xq'' in p.u. (Unsaturated or saturated)	
	Stator leakage reactance Xl in p.u.	
	Saturation constant S (1.0) in p.u.	
	Saturation constant S (1.2) in p.u.	
GENSAE OR **GENSAL**	Direct axis open circuit transient time constant Tdo' in sec	
	Direct axis open circuit sub-transient time constant Tdo'' in sec	
	Quadrature axis open circuit sub-transient time constant Tqo'' in sec	
	Inertia constant of total rotating mass H in MW. s/MVA	
	Speed Damping D	
	Direct axis synchronous reactance Xd in p.u. (Unsaturated or saturated)	
	Quadrature axis synchronous reactance Xq in p.u. (Unsaturated or saturated)	
	Direct axis transient synchronous reactance Xd' in p.u. (Unsaturated or saturated)	
	Direct axis sub-transient synchronous reactance Xd'' in p.u. (Unsaturated or saturated) = Quadrature axis sub-transient synchronous reactance Xq'' in p.u. (Unsaturated or saturated)	
	Stator leakage reactance Xl in p.u.	
	Saturation constant S (1.0) in p.u.	
	Saturation constant S (1.2) in p.u.	

While entering the values in above table, following relationship must be kept:

Xd>Xq>Xq’≥Xd’>Xq”≥Xd’’

Tdo’>Td’>Tdo’’>Td’’

Tqo’’>Tq’>Tqo’’>Tq’’

3.3 Excitation system model:

If a generic model is used, the first step must be to identify what type of exciter is present in the excitation system. The IEEE Std 421.5 (IEEE Recommended Practice for Excitation System Models for Power System Stability Studies published on 26th Aug 2016) has published several generic models, which are classified into three groups:

- Type DC: for excitation systems with a DC exciter
- Type AC: for excitation systems with an AC exciter
- Type ST: for excitation systems with a static exciter

The following table shows the types of models separated into their respective groups.

DC exciter	AC exciter	Static excitation system
Type DC1A	Type AC1A	Type ST1A
Type DC2A	Type AC2A	Type ST2A
Type DC3A	Type AC4A	Type ST3A
Type DC4B	Type AC5A	Type ST4B
	Type AC6A	Type ST5B
	Type AC7B	Type ST6B
	Type AC8B	Type ST7B

Category	Parameter Description	Data
DC Exciter		
ESDC1A OR ESDC2A	TR regulator input filter time constant (sec)	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	TB (s), lag time constant	
	TC (s), lead time constant	
	VRMAX (pu) regulator output maximum limit or Zero	
	VRMIN (pu) regulator output minimum limit	
	KE (pu) exciter constant related to self-excited field	
	TE (> 0) rotating exciter time constant (sec)	
	KF (pu) rate feedback gain	
	TF1 (> 0) rate feedback time constant (sec)	
	Switch	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	
ESDC3A	TR regulator input filter time constant (sec)	
	KV (pu) limit on fast raise/lower contact setting	
	VRMAX (pu) regulator output maximum limit or Zero	
	VRMIN (pu) regulator output minimum limit	
	TRH (> 0) Rheostat motor travel time (sec)	
	TE (> 0) exciter time-constant (sec)	
	KE (pu) exciter constant related to self-excited field	
	VEMIN (pu) exciter minimum limit	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	

Category	Parameter Description	Data
DC Exciter		
ESDC4B	TR regulator input filter time constant (sec)	
	KP (pu) (> 0) voltage regulator proportional gain	
	KI (pu) voltage regulator integral gain	
	KD (pu) voltage regulator derivative gain	
	TD voltage regulator derivative channel time constant (sec)	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KA (> 0) (pu) voltage regulator gain	
	TA voltage regulator time constant (sec)	
	KE (pu) exciter constant related to self-excited field	
	TE (> 0) rotating exciter time constant (sec)	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	VEMIN (pu) minimum exciter voltage output	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	
AC Exciter		
ESAC1A	TR regulator input filter time constant (sec)	
	TB (s), lag time constant	
	TC (s), lead time constant	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	TE (> 0) rotating exciter time constant (sec)	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	KD (pu) demagnetizing factor, function of AC exciter reactance	
	KE (pu) exciter constant related to self-excited field	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	

Category	Parameter Description	Data
AC Exciter		
ESAC2A	TR regulator input filter time constant (sec)	
	TB (s), lag time constant	
	TC (s), lead time constant	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	KB, Second stage regulator gain	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	TE (> 0) rotating exciter time constant (sec)	
	VFEMAX, parameter of VEMAX, exciter field maximum output	
	KH, Exciter field current feedback gain	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	KD (pu) demagnetizing factor, function of AC exciter reactance	
	KE (pu) exciter constant related to self-excited field	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	
ESAC3A	TR regulator input filter time constant (sec)	
	TB (s), lag time constant	
	TC (s), lead time constant	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	TE (> 0) rotating exciter time constant (sec)	
	VEMIN (pu) minimum exciter voltage output	
	KR (>0), Constant associated with regulator and alternator field power supply	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	KN, Exciter feedback gain	
	EFDN, A parameter defining for which value of UF the feedback gain shall change from KF to KN	
	KC, rectifier regulation factor (pu)	
	KD, exciter regulation factor (pu)	
	KE (pu) exciter constant related to self-excited field	
	VFEMAX, parameter of VEMAX, exciter field maximum output	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	

Category	Parameter Description	Data
AC Exciter		
ESAC4A	TR regulator input filter time constant (sec)	
	VIMAX, Maximum value of limitation of the integrator signal VI in p. u	
	VIMIN, Minimum value of limitation of the signal VI in p.u.	
	TB (s), lag time constant	
	TC (s), lead time constant	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KC, rectifier regulation factor (pu)	
ESAC5A	TR regulator input filter time constant (sec)	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KE (pu) exciter constant related to self-excited field	
	TE (> 0) rotating exciter time constant (sec)	
	KF (pu) rate feedback gain	
	TF1 (sec), Regulator stabilizing circuit time constant in seconds	
	TF2 (sec), Regulator stabilizing circuit time constant in seconds	
	TF3 (sec), Regulator stabilizing circuit time constant in seconds	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	

Category	Parameter Description	Data
AC Exciter		
AC6A	TR regulator input filter time constant (sec)	
	KA (> 0) (pu) voltage regulator gain	
	TA (s), voltage regulator time constant	
	TK (sec), Lead time constant	
	TB (s), lag time constant	
	TC (s), lead time constant	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	TE (> 0) rotating exciter time constant (sec)	
	VFELIM, Exciter field current limit reference	
	KH, Damping module gain	
	VHMAX, damping module limiter	
	TH (sec), damping module lag time constant	
	TJ (sec), damping module lead time constant	
	KC, rectifier regulation factor (pu)	
	KD, exciter regulation factor (pu)	
	KE (pu) exciter constant related to self-excited field	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	

Category	Parameter Description	Data
	AC Exciter	
AC7B	TR (sec) regulator input filter time constant	
	KPR (pu) regulator proportional gain	
	KIR (pu) regulator integral gain	
	KDR (pu) regulator derivative gain	
	TDR (sec) regulator derivative block time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KPA (pu) voltage regulator proportional gain	
	KIA (pu) voltage regulator integral gain	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	KP (pu)	
	KL (pu)	
	KF1 (pu)	
	KF2 (pu)	
	KF3 (pu)	
	TF3 (sec) time constant (> 0)	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	KD (pu) demagnetizing factor, function of AC exciter reactance	
	KE (pu) exciter constant related to self-excited field	
	TE (pu) exciter time constant (>0)	
	VFEMAX (pu) exciter field current limit (> 0)	
	VEMIN (pu)	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	

Category	Parameter Description	Data
AC Exciter		
AC8B	TR (sec) regulator input filter time constant	
	KPR (pu) regulator proportional gain	
	KIR (pu) regulator integral gain	
	KDR (pu) regulator derivative gain	
	TDR (sec) regulator derivative block time constant	
	VPIDMAX (pu) PID maximum limit	
	VPIDMIN (pu) PID minimum limit	
	KA (pu) voltage regulator proportional gain	
	TA (sec) voltage regulator time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	KD (pu) demagnetizing factor, function of AC exciter reactance	
	KE (pu) exciter constant related to self-excited field	
	TE (pu) exciter time constant (>0)	
	VFEMAX (pu) max exciter field current limit (> 0)	
	VEMIN (pu),	
	E1, exciter flux at knee of curve (pu)	
	SE(E1), saturation factor at knee of curve	
	E2, maximum exciter flux (pu)	
	SE(E2), saturation factor at maximum exciter flux (pu)	
Static Exciter		
ST1A	TR (sec) regulator input filter time constant	
	VIMAX, Controller Input Maximum	
	VIMIN, Controller Input Minimum	
	TC (s), Filter 1st Derivative Time Constant	
	TB (s), l Filter 1st Delay Time Constant	
	TC1 (s), Filter 2nd Derivative Time Constant	
	TB1 (s), Filter 2nd Delay Time Constant	
	KA (pu) voltage regulator proportional gain	
	TA (sec) voltage regulator time constant	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	KLR, Current Input Factor	
	ILR, Current Input Reference	

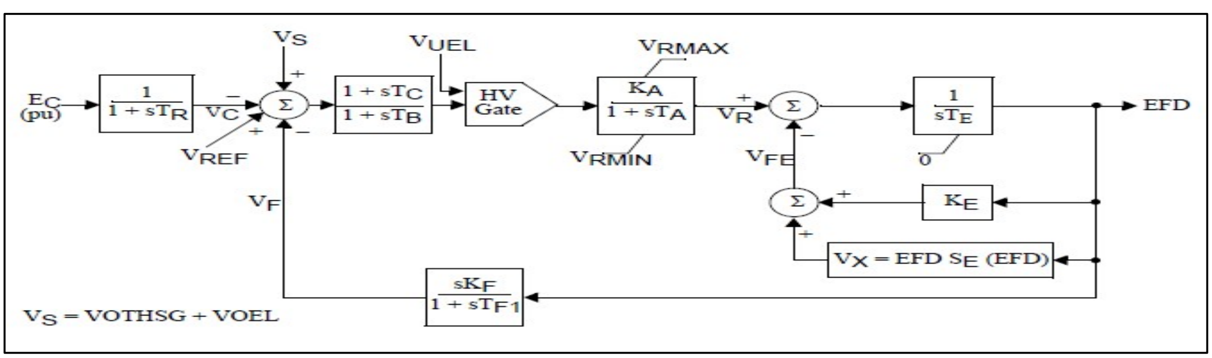
Category	Parameter Description	Data
Static Exciter		
ST2A	TR (sec) regulator input filter time constant	
	KA (pu) voltage regulator proportional gain	
	TA (sec) voltage regulator time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KE (pu) exciter constant related to self-excited field	
	TE (pu) exciter time constant (>0)	
	KF (pu) rate feedback gain	
	TF (> 0) rate feedback time constant (sec)	
	KP (pu) voltage regulator proportional gain	
	KI (pu) voltage regulator integral gain	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	EFDMAX	
ST3A	TR (sec) regulator input filter time constant	
	VIMAX, Maximum value of limitation of the signal VI in p.u.	
	VIMIN, Minimum value of limitation of the signal VI in p.u.	
	KM, Forward gain constant of the inner loop field regulator	
	TC (s), lag time constant	
	TB (s), lead time constant	
	KA (pu) voltage regulator proportional gain	
	TA (sec) voltage regulator time constant	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	KG, Feedback gain constant of the inner loop field regulator	
	KP (pu) voltage regulator proportional gain	
	KI (pu) voltage regulator integral gain	
	VBMAX, Maximum value of limitation of the signal VB in p.u.	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	XL, Reactance associated with potential source	
	VGMAX, Maximum value of limitation of the signal VG in p. u	
	Θ_P (degrees)	
	TM (sec), Forward time constant of the inner loop field regulator	
	VMMAX, Maximum value of limitation of the signal VM in p. u	
	VMMIN, Minimum value of limitation of the signal VM in p.u.	

Category	Parameter Description	Data
	Static Exciter	
ST4B	TR (sec) regulator input filter time constant	
	KPR (pu) regulator proportional gain	
	KIR (pu) regulator integral gain	
	VRMAX (pu) regulator output maximum limit	
	VRMIN (pu) regulator output minimum limit	
	TA (sec) voltage regulator time constant	
	KPM, Regulator gain	
	KIM, Regulator gain	
	VMMAX, Maximum value of limitation of the signal in p.u.	
	VMMIN, Minimum value of limitation of the signal in p.u.	
	KG	
	KP (pu) voltage regulator proportional gain	
	KI (pu) voltage regulator integral gain	
	VBMAX	
	KC (pu) rectifier loading factor proportional to commutating reactance	
	XL	
	Θ_P (degrees)	
ST5B	TR regulator input filter time constant (sec)	
	TC1 lead time constant of first lead-lag block (voltage regulator channel) (sec)	
	TB1 lag time constant of first lead-lag block (voltage regulator channel) (sec)	
	TC2 lead time constant of second lead-lag block (voltage regulator channel) (sec)	
	TB2 lag time constant of second lead-lag block (voltage regulator channel) (sec)	
	KR (>0) (pu) voltage regulator gain	
	VRMAX (pu) voltage regulator maximum limit	
	VRMIN (pu) voltage regulator minimum limit	
	T1 voltage regulator time constant (sec)	
	KC (pu)	
	TUC1 lead time constant of first lead-lag block (under-excitation channel) (sec)	
	TUB1 lag time constant of first lead-lag block (under-excitation channel) (sec)	
	TUC2 lead time constant of second lead-lag block (under-excitation channel) (sec)	
	TUB2 lag time constant of second lead-lag block (under-excitation channel) (sec)	
	TOC1 lead time constant of first lead-lag block (over-excitation channel) (sec)	
	TOB1 lag time constant of first lead-lag block (over-excitation channel) (sec)	
	TOC2 lead time constant of second lead-lag block (over-excitation channel) (sec)	
	TOB2 lag time constant of second lead-lag block (over-excitation channel) (sec)	

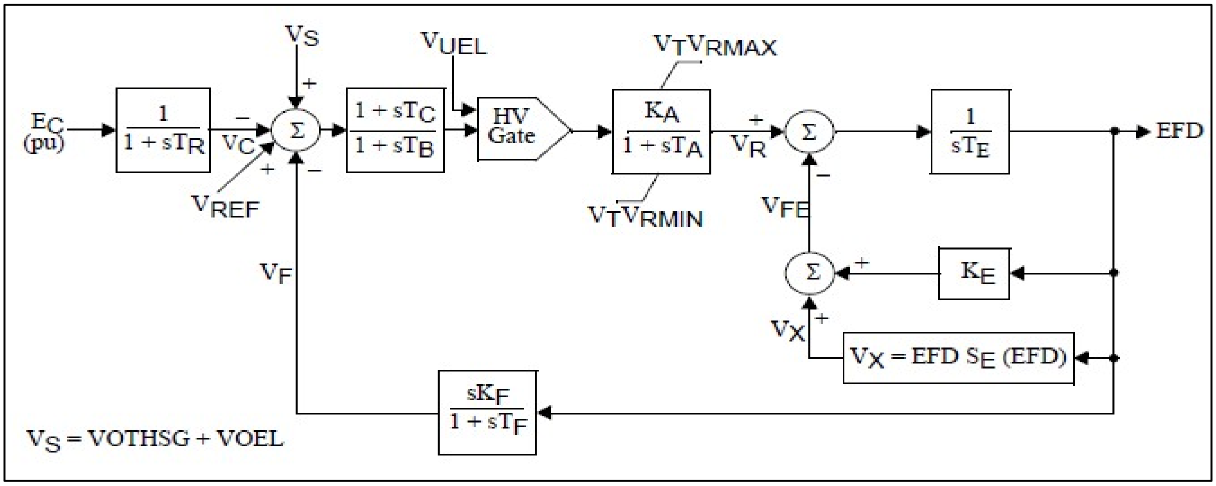
Category	Parameter Description	Data
Static Exciter		
ST6B	TR regulator input filter time constant (sec)	
	KPA (pu) (> 0) voltage regulator proportional gain	
	KIA (pu) voltage regulator integral gain	
	KDA (pu) voltage regulator derivative gain	
	TDA voltage regulator derivative channel time constant (sec)	
	VAMAX (pu) regulator output maximum limit	
	VAMIN (pu) regulator output minimum limit	
	KFF (pu) pre-control gain of the inner loop field regulator	
	KM (pu) forward gain of the inner loop field regulator	
	KCI (pu) exciter output current limit adjustment gain	
	KLR (pu) exciter output current limiter gain	
	ILR (pu) exciter current limit reference	
	VRMAX (pu) voltage regulator output maximum limit	
	VRMIN (pu) voltage regulator output minimum limit	
	KG (pu) feedback gain of the inner loop field voltage regulator	
	TG (> 0) feedback time constant of the inner loop field voltage regulator (sec)	
ST7B	TR regulator input filter time constant (sec)	
	TG lead time constant of voltage input (sec)	
	TF lag time constant of voltage input (sec)	
	Vmax (pu) voltage reference maximum limit	
	Vmin (pu) voltage reference minimum limit	
	KPA (pu) (>0) voltage regulator gain	
	VRMAX (pu) voltage regulator output maximum limit	
	VRMIN (pu) voltage regulator output minimum limit	
	KH (pu) feedback gain	
	KL (pu) feedback gain	
	TC lead time constant of voltage regulator (sec)	
	TB lag time constant of voltage regulator (sec)	
	KIA (pu) (>0) gain of the first order feedback block	
	TIA (>0) time constant of the first order feedback block (sec)	

(i)**DC Exciters Generic model:**

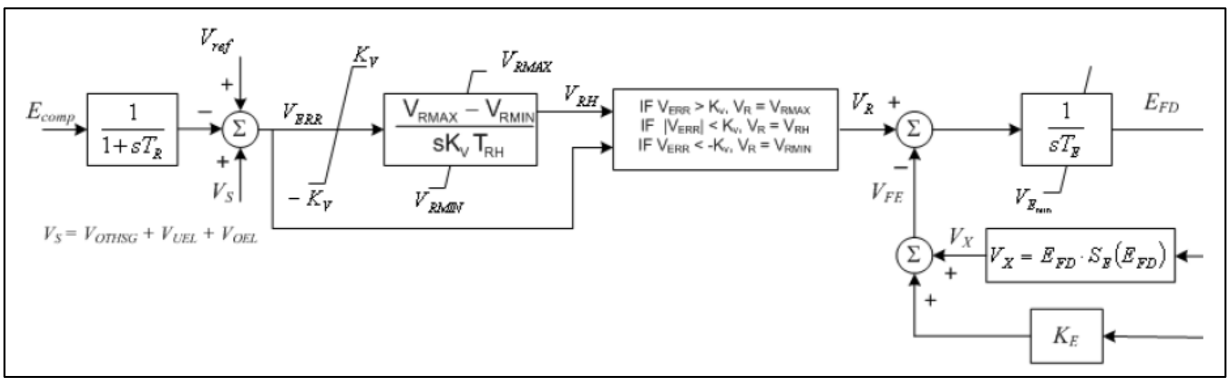
- **Type DC1A: 1992 IEEE type DC1A excitation system model**



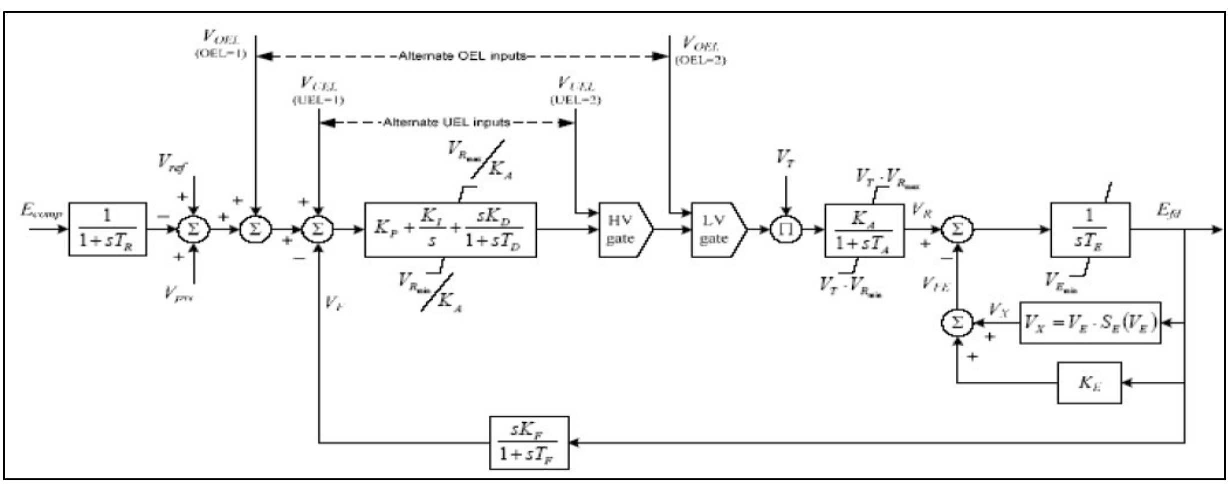
- **Type DC2A: 1992 IEEE type DC2A excitation system model**



- **Type DC3A: IEEE 421.5 2005 DC3A excitation system**

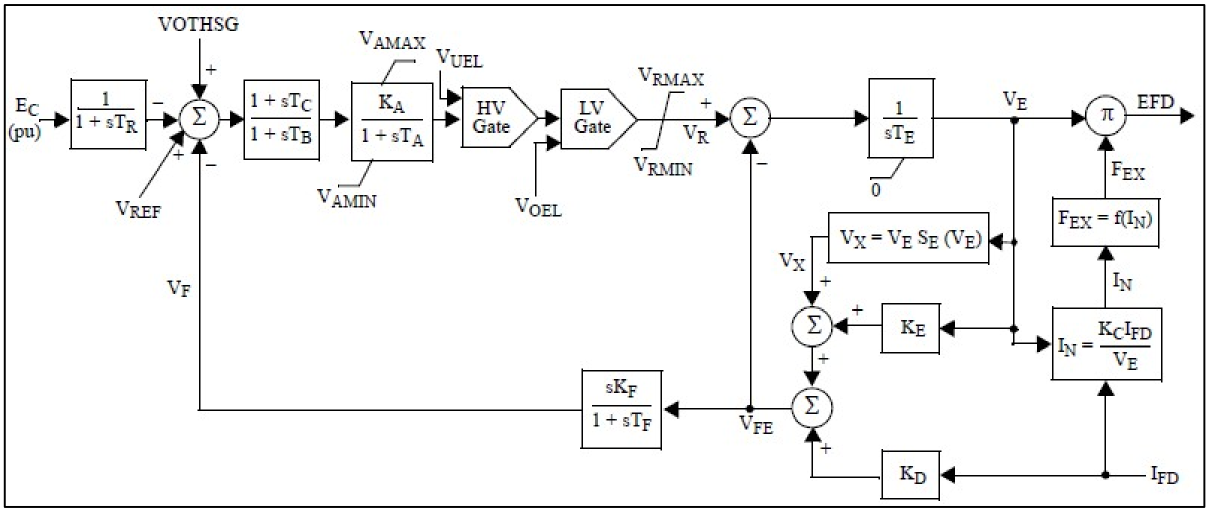


- **Type DC4B: IEEE 421.5 2005 DC4B excitation system**



(ii) AC Exciters Generic Models:

- **Type AC1A: 1992 IEEE type AC1A excitation system model**

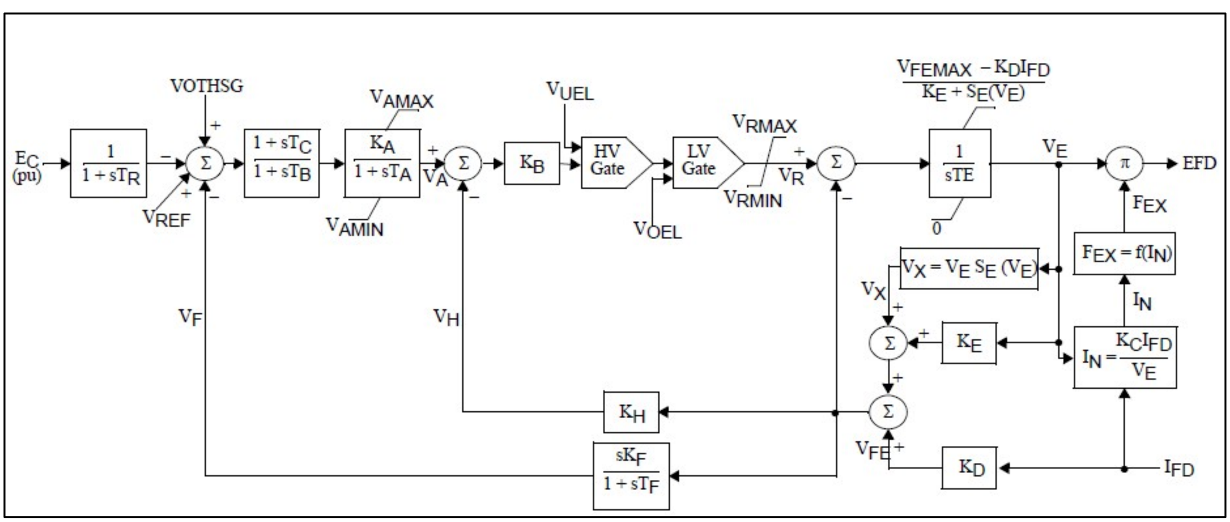


I_N →

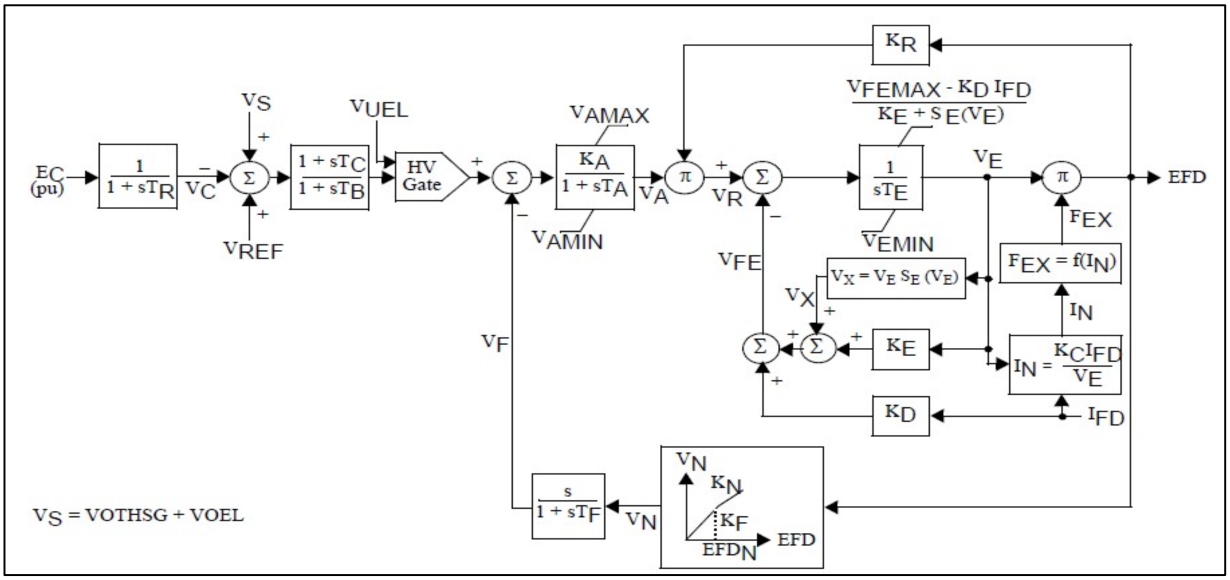
If $I_N \leq 0$	$F_{EX} = 1$
If $I_N \leq 0.433$	$F_{EX} = 1 - 0.577\ I_N$
If $0.433 < I_N < 0.75$	$F_{EX} = \sqrt{0.75 - I_N^2}$
If $I_N \geq 0.75$	$F_{EX} = 1.732(1 - I_N)$
If $I_N > 1$	$F_{EX} = 0$

→ F_{EX}

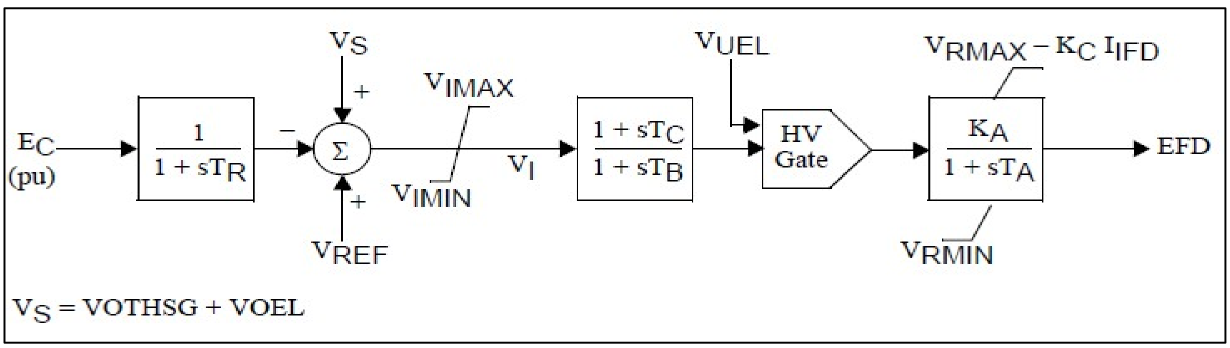
- **Type AC2A: 1992 IEEE type AC2A excitation system model**



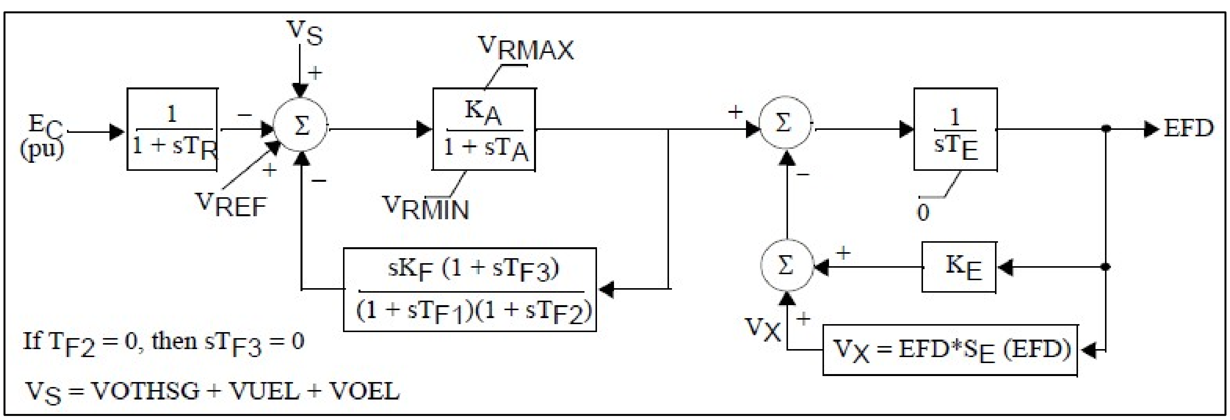
➢ **Type AC3A: 1992 IEEE type AC3A excitation system model**



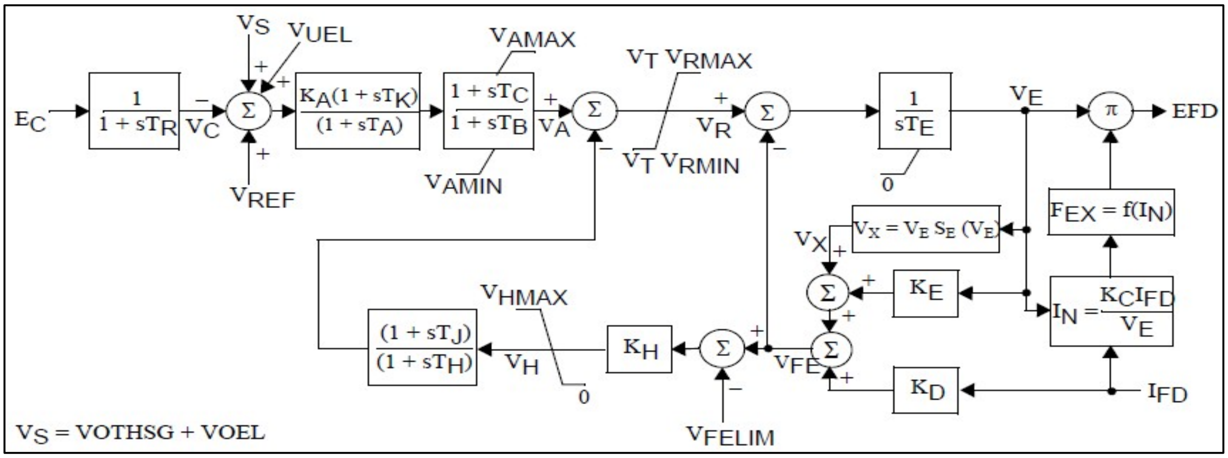
➢ **Type AC4A: 1992 IEEE type AC4A excitation system model**



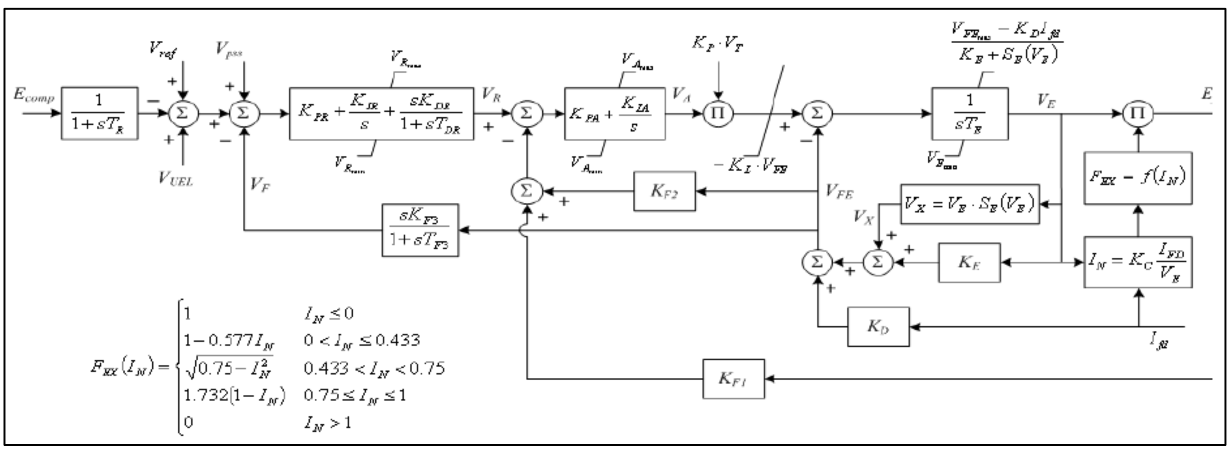
➢ **Type AC5A: 1992 IEEE type AC5A excitation system model**



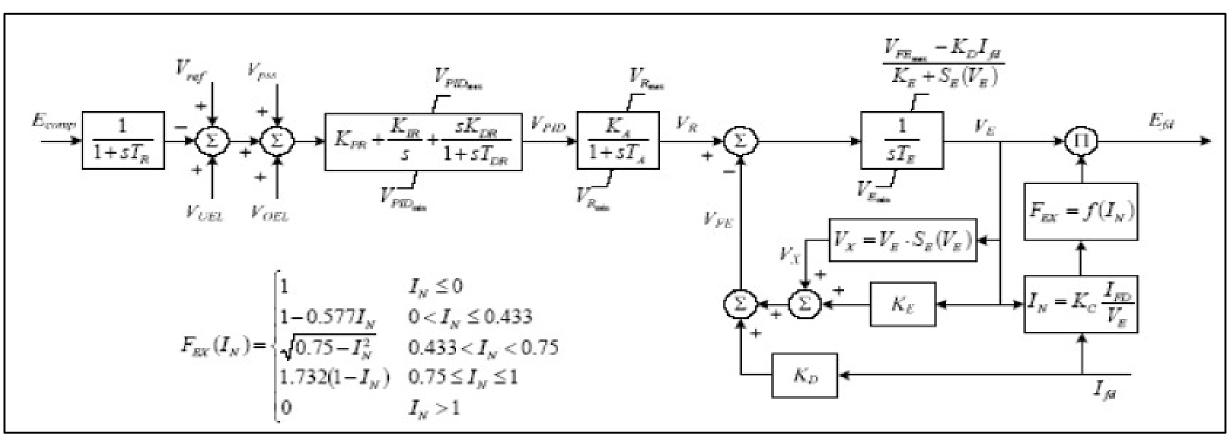
- **Type AC6A: IEEE 421.5 excitation system model**



- **Type AC7B: IEEE 421.5 2005 AC7B excitation system**

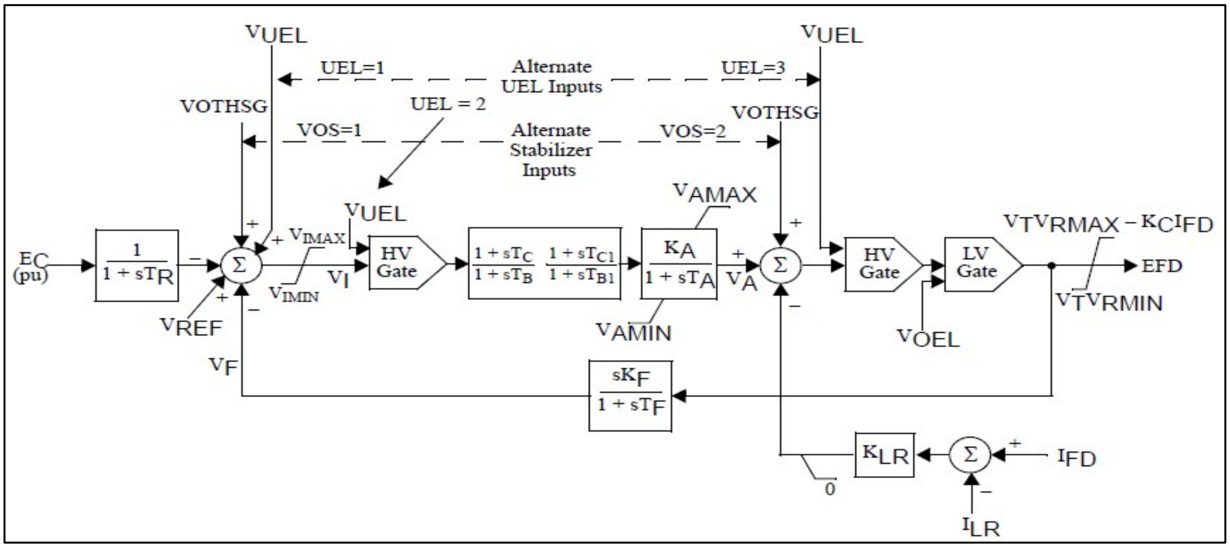


- **Type AC8B: IEEE 421.5 2005 AC8B excitation system**

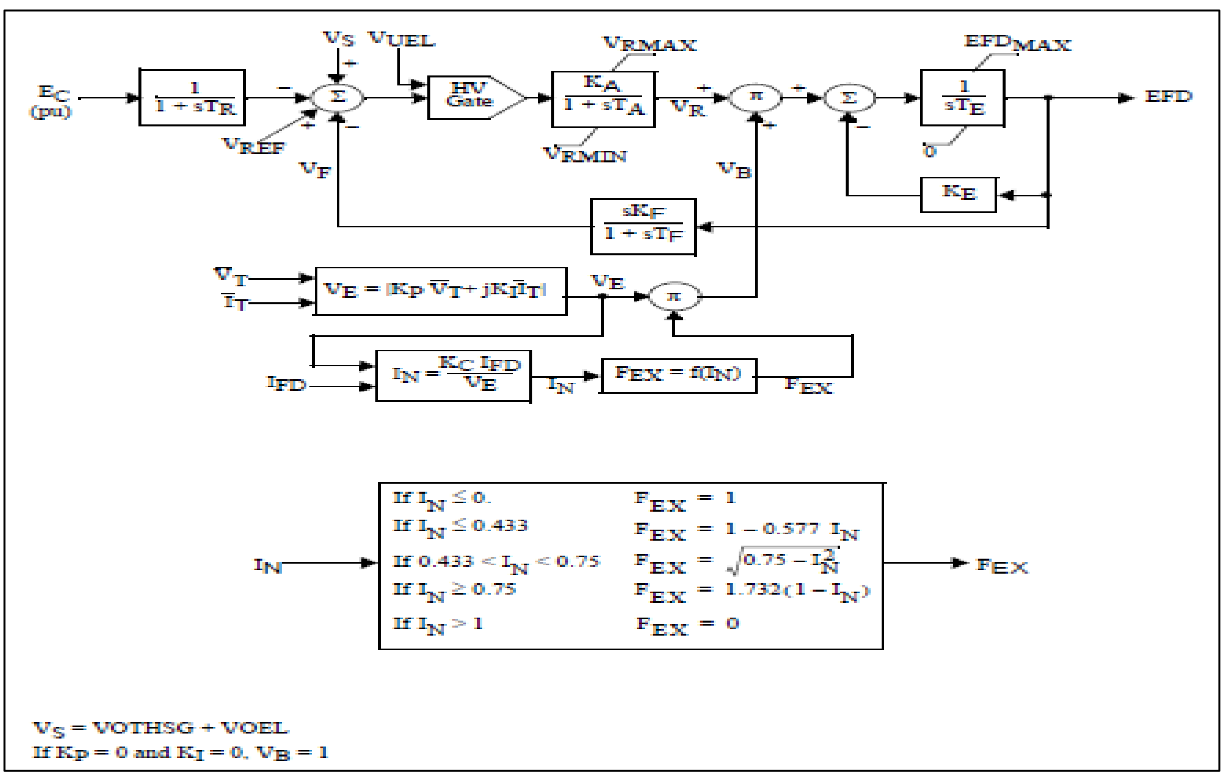


(iii) **Commonly Used Static Exciters Generic Models block diagrams:**

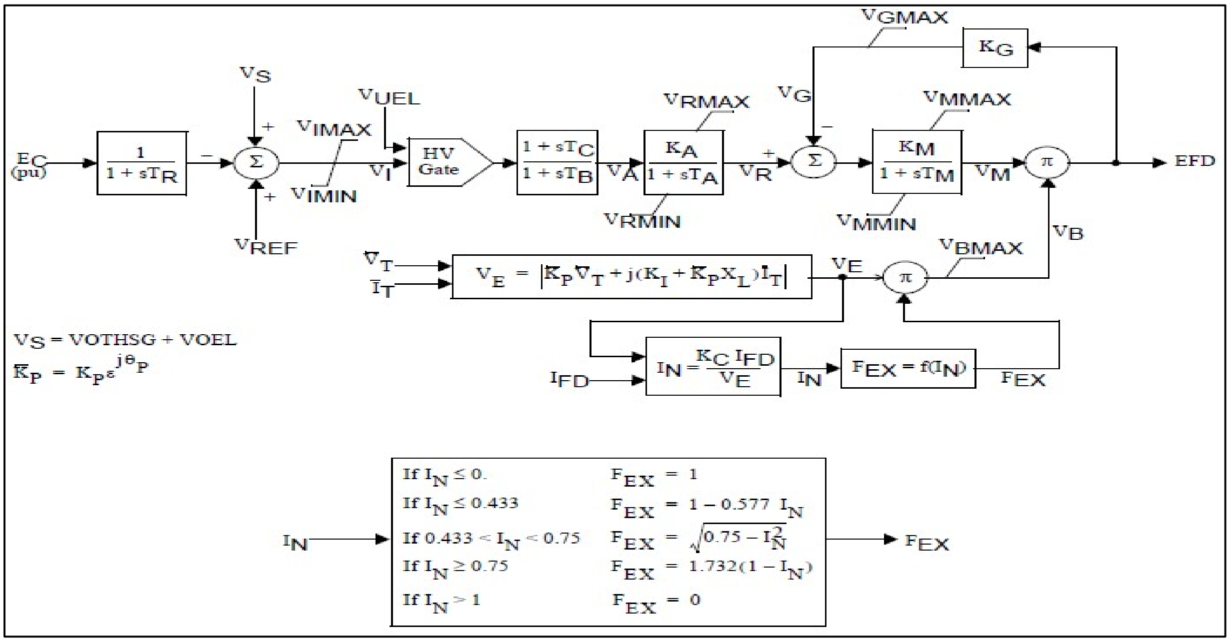
- **Type ST1A: 1992 IEEE type ST1A excitation system model**



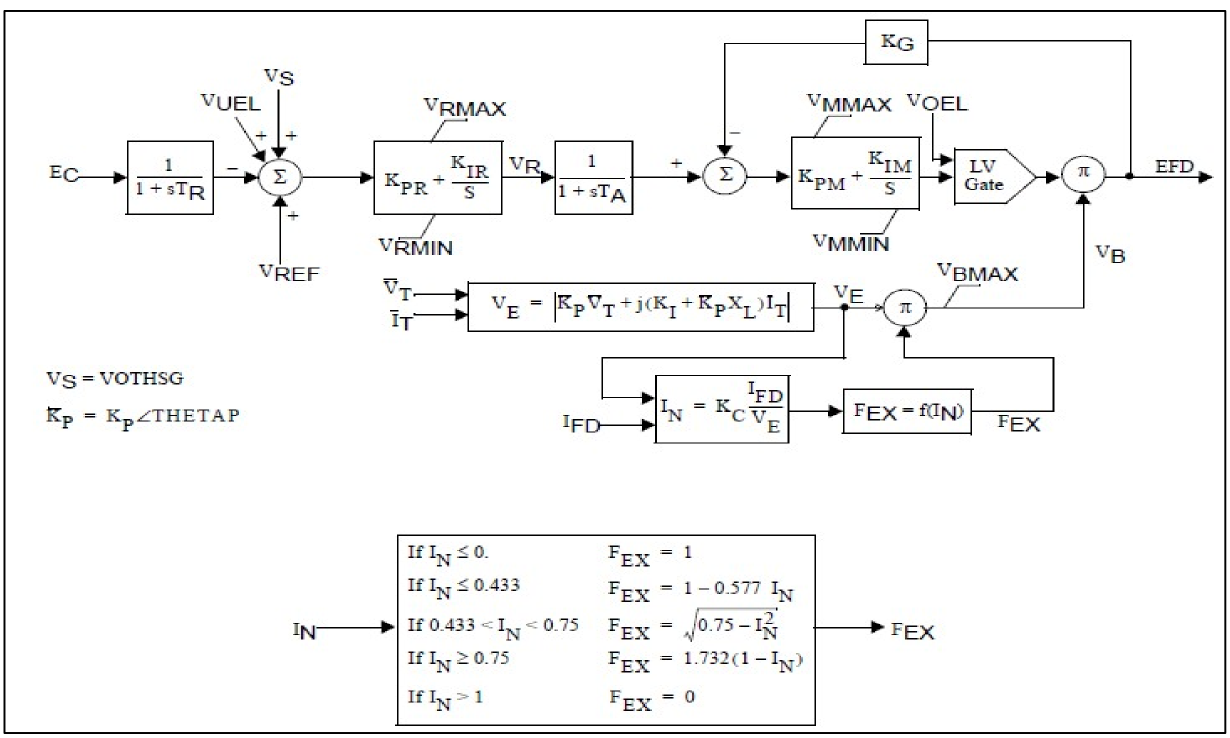
- **Type ST2A: 1992 IEEE type ST2A excitation system model**



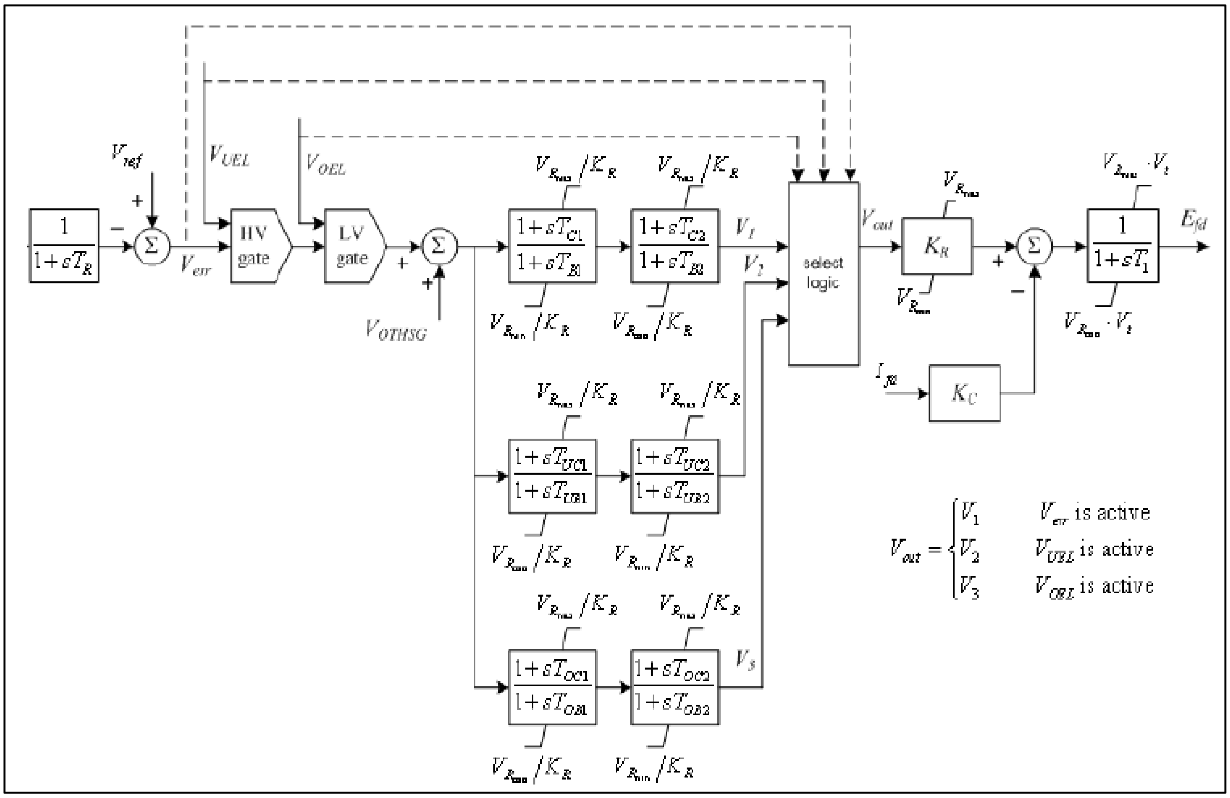
➢ **Type ST3A: 1992 IEEE type ST3A excitation system model**



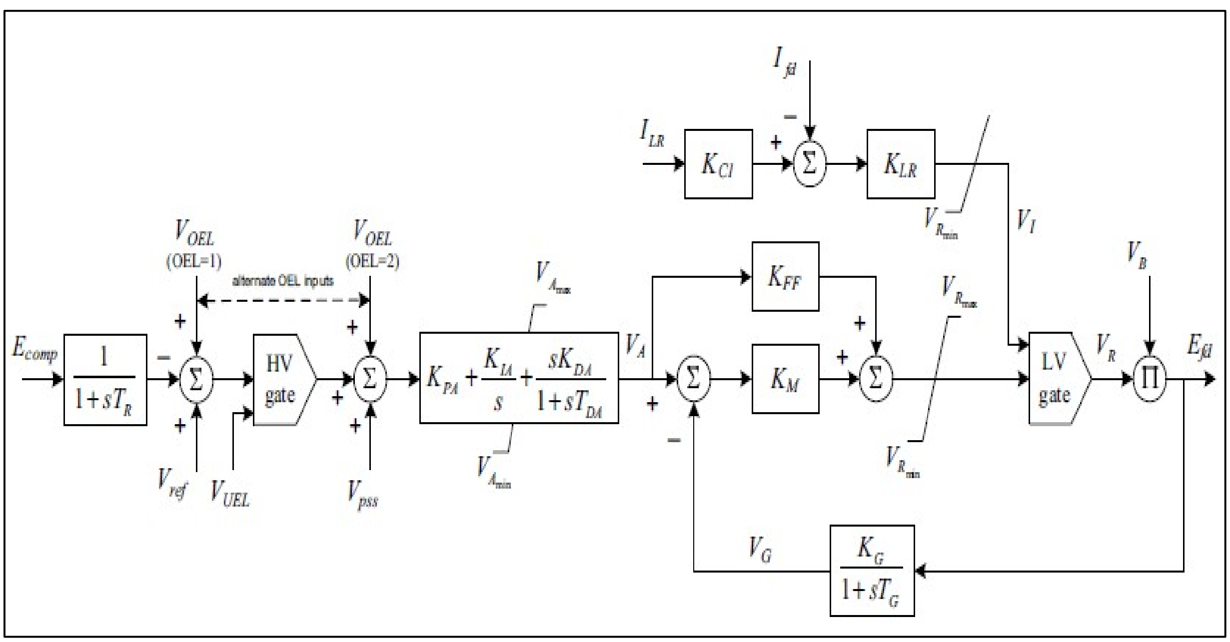
➢ **Type ST4B: IEEE type ST4B potential or compounded source-controlled rectifier exciter**



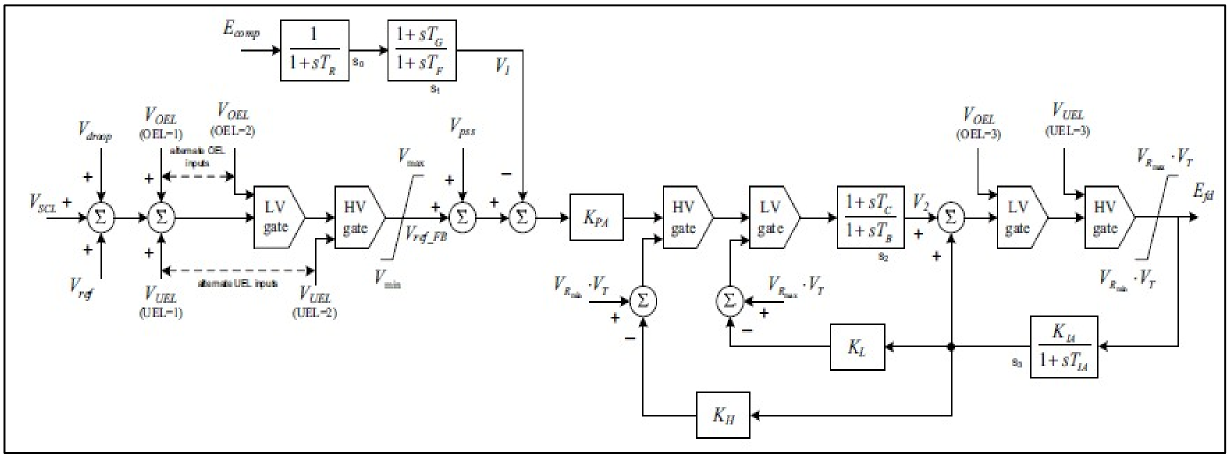
- **Type ST5B: IEEE 421.5 2005 ST5B excitation system**



- **Type ST6B: IEEE 421.5 2005 ST6B excitation system**



- **Type ST7B: IEEE 421.5 2005 ST7B excitation system**



Source-PSSE Model Library

3.4 Power system stabilizer:

The function of the PSS is to add to the unit's characteristic electromechanical oscillations. This is achieved by modulating excitation to develop a component in electrical torque in phase with rotor speed deviations.

The most important aspect when considering a PSS model is the number of inputs. The following table shows the type of models separated based on the inputs:

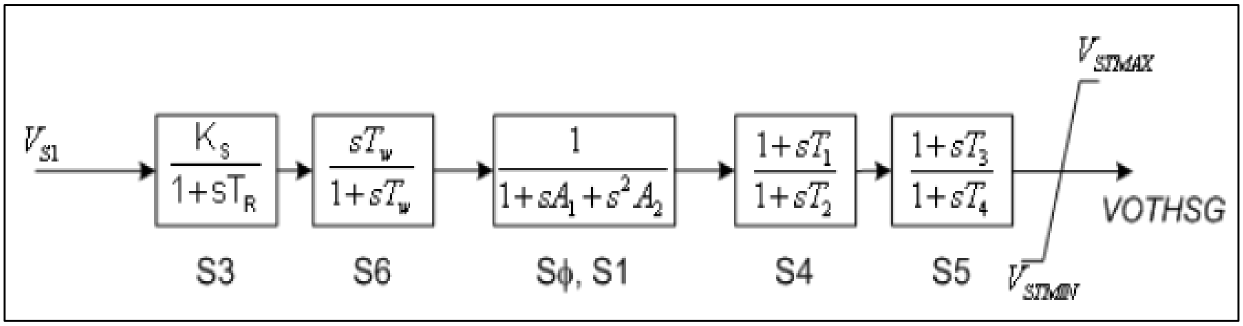
Type	Inputs	Remarks
PSS1A	Single input	Two lead-lags Input can either be speed, frequency or power
PSS2B	Dual input	Integral of accelerating power Speed and Power Most common type Supersedes PSS2A (three versus two lead lags)
PSS3B	Dual input	Power and rotor angular frequency deviation Stabilising signal is a vector sum of processed signals Not very common

Category	Parameter Description	Data
	Stabilizer Models	
PSS1A	A1, Filter coefficient	
	A2, Filter coefficient	
	TR, transducer time constant	
	0	
	0	
	0	
	T1, 1st Lead-Lag Derivative Time Constant	
	T2, 1st Lead-Lag Delay Time Constant	
	T3, 2nd Lead-Lag Derivative Time Constant	
	T4, 2nd Lead-Lag Delay Time Constant	
	Tw, Washout Time Constant	
	Tw, Washout Time Constant	
	Ks, input channel gain	
	VSTMAX, Controller maximum output	
	VSTMAX, Controller minimum output	
	0	
	0	

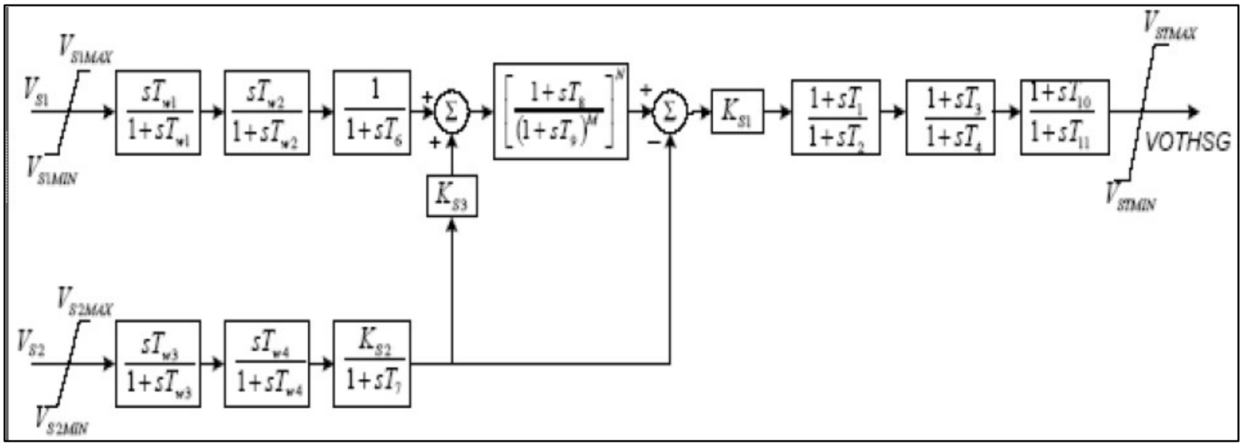
Category	Parameter Description	Data
Stabilizer Models		
PSS2B	TW1, 1st Washout 1th Time Constant	
	TW2, 1st Washout 2th Time Constant	
	T6, 1st Signal Transducer Time Constant	
	TW3, 2nd Washout 1th Time Constant	
	TW4, 2nd Washout 2th Time Constant	
	T7, 2nd Signal Transducer Time Constant	
	KS2, 2nd Signal Transducer Factor	
	KS3, Washouts Coupling Factor	
	T8, Ramp Tracking Filter Deriv. Time Constant	
	T9, Ramp Tracking Filter Delay Time Constant	
	KS1, PSS Gain	
	T1, 1st Lead-Lag Derivative Time Constant	
	T2, 1st Lead-Lag Delay Time Constant	
	T3, 2nd Lead-Lag Derivative Time Constant	
	T4, 2nd Lead-Lag Delay Time Constant	
	T10, 3rd Lead-Lag Derivative Time Constant	
	T11, 3rd Lead-Lag Delay Time Constant	
	VS1MAX, Input 1 Maximum limit	
	VS1MIN, Input 1 Minimum limit	
	VS2MAX, Input 2 Maximum limit	
	VS2MIN, Input 2 Minimum limit	
	VSTMAX, Controller Maximum Output	
	VSTMIN, Controller Minimum Output	
PSS3B	KS1 (pu) (≠0), input channel #1 gain	
	T1 input channel #1 transducer time constant (sec)	
	Tw1 input channel #1 washout time constant (sec)	
	KS2 (pu) (□0), input channel #2 gain	
	T2 input channel #2 transducer time constant (sec)	
	Tw2 input channel #2 washout time constant (sec)	
	Tw3 (0), main washout time constant (sec)	
	A1, Filter coefficient	
	A2, Filter coefficient	
	A3, Filter coefficient	
	A4, Filter coefficient	
	A5, Filter coefficient	
	A6, Filter coefficient	
	A7, Filter coefficient	
	A8, Filter coefficient	
	VSTMAX, Controller maximum output	
	VSTMAX, Controller minimum output	

Commonly Used Power System Stabilizer generic models block diagrams:

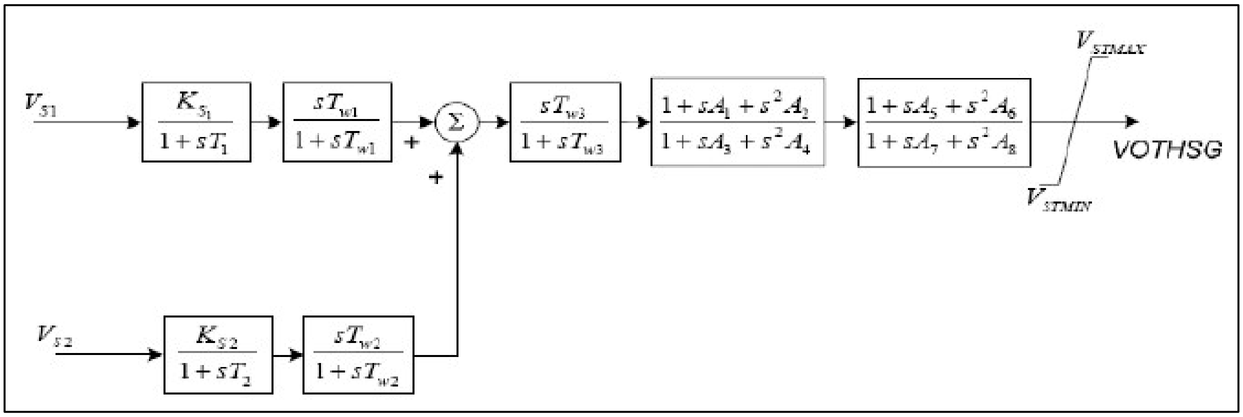
- **PSS1A: IEEE Std. 421.5-2005 PSS1A Single-Input Stabilizer model**



- **PSS2B: IEEE 421.5 2005 PSS2B IEEE dual-input stabilizer model**



- **PSS3B: IEEE Std. 421.5 2005 PSS3B IEEE dual-input stabilizer model**



Source-PSSE Model Library

3.5 Generic models for turbine-governor:

The following table is a list for generic models of steam turbines:

Type	Name	Remarks
BBGOV1	Brown-Boveri turbine governor model	Mainly used for steam turbine with electrical damping feedback
TGOV1	Steam-turbine governor	Mainly used for steam turbine with reheater
CRCMGV	Cross-compound turbine	-
IEEEG1	IEEE type 1 Speed-Governor Model	Used to represent non-reheat, tandem compound, and cross compound types.
IEEEG2	IEEE Type 2 Speed-Governing Model	Linearized model for representing a hydro turbine-governor and penstock dynamics
IEEEG3	IEEE type 3 turbine-governor model	Includes a more complex representation of the governor controls than IEEEG2 does
IEESGO	IEEE Standard Model	Simple model of reheat steam turbine
TGOV2	Steam –turbine governor with fast valving	Fast valving model of steam turbine
TGOV3	Modified IEEE Type 1 Speed-Governing Model with fast valving	Modification of IEEEG! For fast valving studies
TGOV4	Modified IEEE Type 1 Speed-Governing Model with PLU and EVA	Model of steam turbine and boiler, explicit action for both control valve (CV) and inlet valve (IV), main reheat and LP steam effects, and boiler
TGOV5	IEEE Type 1 Speed-Governor Model Modified to Include Boiler Controls	Most common type of governor model, based on TGOV1 with boiler controls
TURCZT	Czech hydro or steam turbine governor model	General-purpose hydro and thermal turbine-governor model. Penstock dynamic is not included in the model

Source: PSSE Model Library, for models other than the above list refer to

https://w3.usa.siemens.com/smartgrid/us/en/transmission-grid/products/grid-analysis-tools/transmission-system-planning/transmission-system-planning-tab/pages/user-support.aspx

Category	Parameter Description	Data
TURBINE GOVERNOR model		
BBGOV1	fcut (>=0) (pu), cut off frequency	
	KS, frequency gain	
	KLS (> 0)	
	KG	
	KP, power regulator gain	
	TN (sec) (> 0)	
	KD, damping gain	
	TD (sec) (> 0), damping time constant	
	T4 (sec), high pressure time constant	
	K2, intermediate pressure time constant	
	T5 (sec), intermediate re-heater time constant	
	K3, high pressure time constant	
	T6 (sec), re-heater time constant	
	T1 (sec), measuring transducer time constant	
	SWITCH	
	PMAX, maximum power output limiter	
	PMIN, minimum power output limiter	
TGOV1	R, Permanent Droop	
	T1 (>0) (sec), Steam bowl time constant	
	VMAX, Maximum valve position	
	VMIN, Minimum valve position	
	T2 (sec), Time constant	
	T3 (>0) (sec), reheater time constant	
	Dt, Turbine damping coefficient	
	VMAX, VMIN, Dt and R, are in per unit on generator MVA base. *T2/T3 = high-pressure fraction.*	
CRCMGV	PMAX (HP)1, maximum HP value position (on generator base)	
	R (HP), HP governor droop	
	T1 (HP) (>0), HP governor time constant	
	T3 (HP) (>0), HP turbine time constant	
	T4 (HP) (>0), HP turbine time constant	
	T5 (HP) (>0), HP reheater time constant	
	F (HP), fraction of HP power ahead of reheater	
	DH (HP), HP damping factor (on generator base)	
	PMAX (LP), maximum LP value position (on generator base)	
	R (LP), LP governor droop	
	T1 (LP) (>0), LP governor time constant	
	T3 (LP) (>0), LP turbine time constant	
	T4 (LP) (>0), LP turbine time constant	
	T5 (LP) (>0), LP turbine time constant	
	F (LP), fraction of LP power ahead of reheater	
	DH (LP), LP damping factor (on generator base)	

Category	Parameter Description	Data
TURBINE GOVERNOR model		
IEEEG1	K, Governor gain, (1/droop) pu	
	T1 (sec), Lag time constant (sec)	
	T2 (sec), Lead time constant (sec)	
	T3 (> 0) (sec), valve position time constant	
	Uo (pu/sec), maximum valve opening rate	
	Uc (< 0) (pu/sec), maximum valve closing rate	
	PMAX (pu on machine MVA rating)	
	PMIN (pu on machine MVA rating)	
	T4 (sec), time constant for steam inlet	
	K1, HP fraction	
	K2, LP fraction	
	T5 (sec), Time Constant for Second Boiler Pass [s]	
	K3, HP Fraction	
	K4, LP fraction	
	T6 (sec), Time Constant for Third Boiler Pass [s]	
	K5, HP Fraction	
	K6, LP fraction	
	T7 (sec), Time Constant for Fourth Boiler Pass [s]	
	K7, HP Fraction	
	K8, LP fraction	
IEEEG2	K, Governor gain	
	T1 (sec), Governor lag time constant	
	T2 (sec), Governor lead time constant	
	T3 (>0) (sec), Gate actuator time constant	
	PMAX (pu on machine MVA rating), gate maximum	
	PMIN (pu on machine MVA rating), gate minimum	
	T4 (>0) (sec), water starting time	
IEEEG3	TG, (>0) (sec), gate servomotor time constant	
	TP (>0) (sec), pilot value time constant	
	Uo (pu per sec), opening gate rate limit	
	Uc (pu per sec), closing gate rate limit (< 0)	
	PMAX maximum gate position (pu on machine MVA rating)	
	PMIN minimum gate position (pu on machine MVA rating)	
	σ, permanent speed droop coefficient	
	δ, transient speed droop coefficient	
	TR, (>0) (sec), Dashpot time constant	
	TW (>0) (sec), water starting time	
	a11 (>0), Turbine coefficient	
	a13, Turbine coefficient	
	a21, Turbine coefficient	
	a23 (>0), Turbine coefficient	

Category	Parameter Description	Data
TURBINE GOVERNOR model		
IEESGO	T1, Controller Lag	
	T2, Controller Lead Compensation	
	T3, Governor Lag (> 0)	
	T4, Delay Due to Steam Inlet Volumes	
	T5, Reheater Delay	
	T6, Turbine, pipe, hood Delay	
	K1, 1/Per Unit Regulation	
	K2, Fraction	
	K3, fraction	
	PMAX, Upper Power Limit	
	PMIN, Lower Power Limit	
TGOV2	R (pu), permanent droop	
	T1 (>0) (sec), Steam bowl time constant	
	VMAX (pu), Maximum valve position	
	VMIN (pu), Minimum valve position	
	K (pu), Governor gain	
	T3 (>0) (sec), Time constant	
	Dt (pu), Turbine damping coefficient	
	Tt (>0) (sec), Valve time constant	
	TA, Valve position at time 2 (fully closed after fast valving initialization)	
	TB, Valve position at time 3 (start to reopen after fast valving initialization)	
	TC, Valve position at time 4 (again fully open after fast valving initializations)	
TGOV3	K, Governor gain	
	T1 (sec), Governor lead time constant	
	T2 (sec), Governor lag time constant	
	T3 (>0) (sec), Valve positioner time constant	
	Uo, Maximum valve opening velocity	
	Uc (< 0), Maximum valve closing velocity	
	PMAX, Maximum valve opening	
	PMIN, Minimum valve opening	
	T4 (sec), Inlet piping/steam bowl time constant	
	K1, Fraction of turbine power developed after first boiler pass	
	T5 (> 0) (sec), Time constant of second boiler pass	
	K2, Fraction of turbine power developed after second boiler pass	
	T6 (sec), Time constant of crossover or third boiler pass	
	K3, Fraction of hp turbine power developed after crossover or third boiler pass	
	TA (sec), Valve position at time 2 (fully closed after fast valving initializations)	
	TB (sec), Valve position at time 3 (start to reopen after fast valving initializations)	
	TC (sec), Valve position at time 4 (again fully open after fast valving initializations)	
	PRMAX (pu), Max. pressure in reheater	

Category	Parameter Description	Data
TURBINE GOVERNOR model		
	K, The inverse of the governor speed droop	
	T1 (sec), The governor controller lag time constant	
	T2 (sec), The governor controller lead time constant	
	T3 (>0) (sec), The valve servomotor time constant for the control valves	
	Uo, The control valve open rate limit	
	Uc (<0), The control valve close rate limit	
	KCAL	
	T4 (sec), The steam flow time constant	
	K1	
	T5 (> 0) (sec)	
	K2	
	T6 (sec)	
	PRMAX	
	KP	
	KI	
	TFuel (sec)	
	TFD1 (sec)	
	TFD2 (sec)	
	Kb	
	Cb (> 0) (sec)	
	TIV (> 0) (sec)	
	UOIV	
	UCIV	
	R (>0)	
TGOV4	Offset	
	CV position demand characteristic	
	CV #2 offset	
	CV #3 offset	
	CV #4 offset	
	IV position demand characteristic	
	IV #2 offset	
	CV valve characteristic	
	IV valve characteristic	
	CV starting time for valve closing (sec)	
	CV closing rate (pu/sec)	
	Time closed for CV #1 (sec)	
	Time closed for CV #2	
	Time closed for CV #3	
	Time closed for CV #4	
	IV starting time for valve closing (sec)	

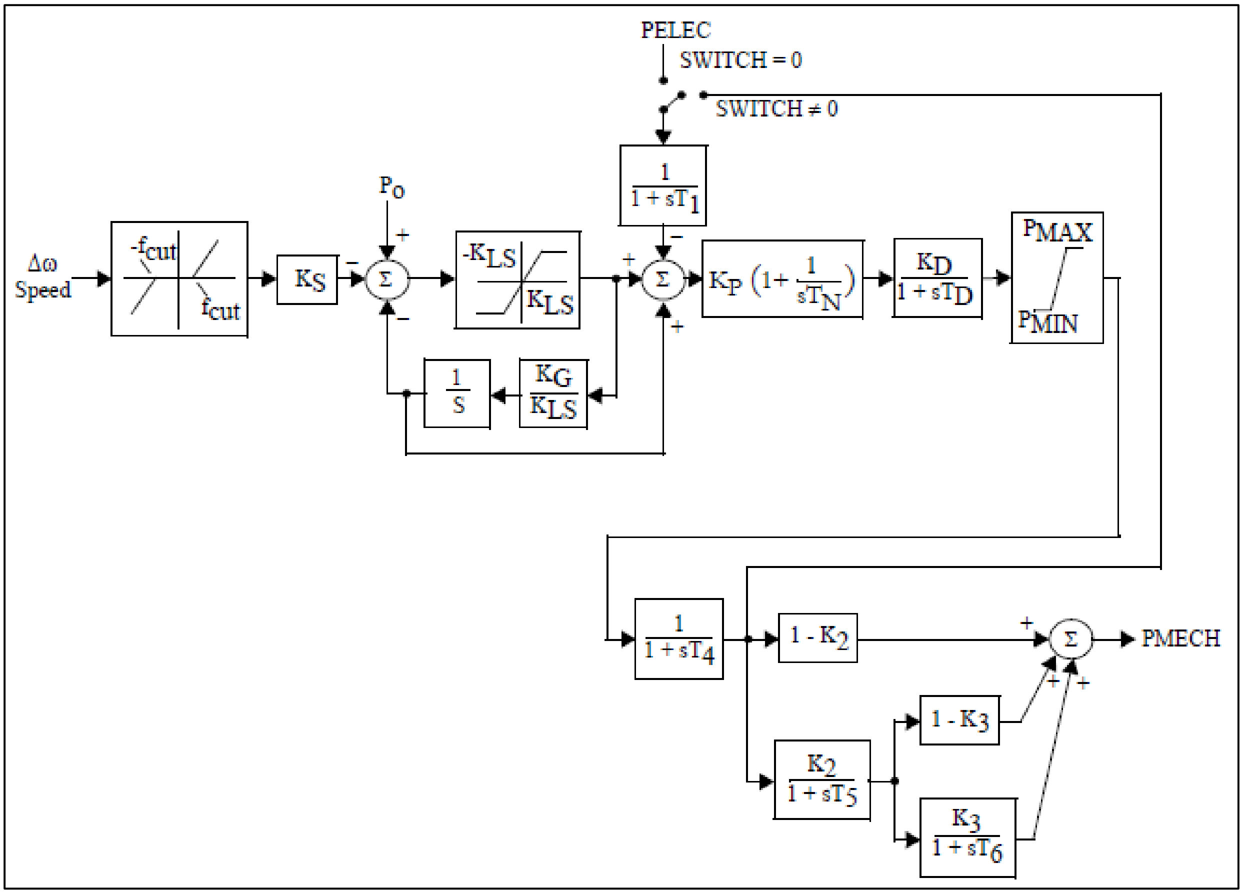
Category	Parameter Description	Data
TURBINE GOVERNOR model		
TGOV4	IV closing rate (pu/sec)	
	Time closed for IV #1 (sec)	
	Time closed for IV #2 (sec)	
	TRPLU (>0) (sec)	
	PLU rate level	
	Timer	
	PLU unbalance level	
	TREVA (>0) (sec)	
	EVA rate level	
	EVA unbalance level	
	Minimum load reference (pu)	
	Load reference ramp rate (pu/sec)	

Category	Parameter Description	Data
TURBINE GOVERNOR model		
TGOV5	K, The inverse of the governor speed droop	
	T1 (sec), The governor controller lag time constant	
	T2 (sec), The governor controller lead time constant	
	T3 (>0) (sec), The valve servomotor time constant for the control valves	
	Uo, The control valve open rate limit	
	Uc (<0), The control valve close rate limit	
	VMAX, The maximum valve area	
	VMIN, The minimum valve area	
	T4 (sec), The steam flow time constant	
	K1, The fractions of the HP	
	K2, fractions of the LP	
	T5 (sec), The first reheater time constant	
	K3, The fractions of the HP	
	K4, fractions of the LP	
	T6 (sec), second reheater time constant	
	K5, The fractions of the HP	
	K6, fractions of the LP	
	T7 (sec), crossover time constant	
	K7, The fractions of the HP	
	K8, fractions of the LP	
	K9, The adjustment to the pressure drop coefficient as a function of drum pressure	
	K10, The gain of anticipation signal from main stream flow	
	K11, The gain of anticipation signal from load demand	
	K12, The gain for pressure error bias	
	K13, The gain between MW demand and pressure set point	
	K14, Inverse of load reference servomotor time constant (= 0.0 if load reference does not change).	
	RMAX, The load reference positive rate of change limit	
	RMIN, The load reference negative rate of change limit	
	LMAX, The maximum load reference	
	LMIN, The minimum load reference	
	C1, The pressure drop coefficient	
	C2, The gain for the pressure error bias	
	C3, The adjustment to the pressure set point	
	B, The frequency bias for load reference control	
	CB (>0) (sec), The boiler storage time constant	
	KI, The controller integral gain	
	TI (sec), The controller proportional lead time constant	
	TR (sec), The controller rate lead time constant	
	TR1 (sec), The inherent lag associated with lead TR (usually about TR/10)	
	CMAX, The maximum controller output	

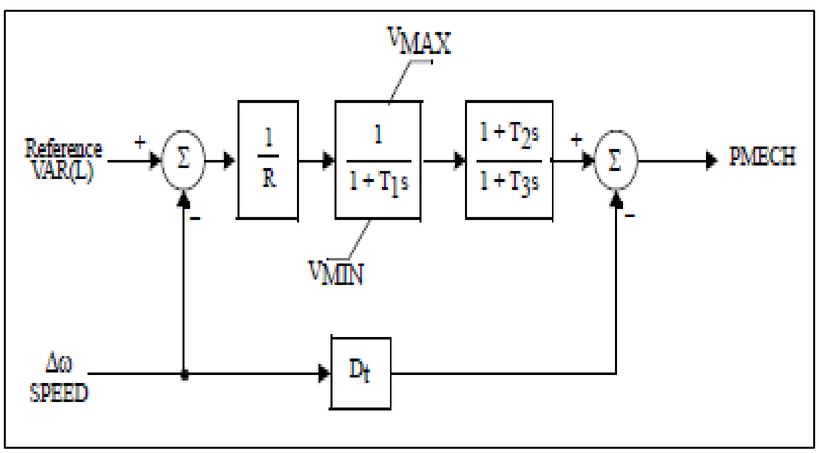
Category	Parameter Description	Data
TURBINE GOVERNOR model		
TGOV5	CMIN, The minimum controller output	
	TD (sec), The time delay in the fuel supply system	
	TF (sec), The fuel and air system time constant	
	TW (sec), The water wall time constant	
	Psp (initial) (>0), The initial throttle pressure set point	
	TMW (sec), The MW transducer time constant	
	KL (0.0 or 1.0), The feedback gain from the load reference	
	KMW (0.0 or 1.0), The gain of the MW transducer	
	DPE (pu pressure), The dead band in the pressure error signal for load reference control	
	• *The fractions of the HP unit's mechanical power developed by the various turbine stages. The sum of K1, K3, K5 andK7 constants should be one for a non-cross-compound unit.* • *Similarly fractions of the LP unit's mechanical power should be zero for a non-cross-compound unit. For a cross-compound unit, the sum of K1 through K8 should equal one.*	
TURCZT	fDEAD (pu), Frequency Dead Band	
	fMIN (pu), Frequency Minimum Deviation	
	fMAX (pu), Frequency Maximum Deviation	
	KKOR (pu), Frequency Gain	
	KM > 0 (pu), Power Measurement Gain	
	KP (pu), Regulator Proportional Gain	
	SDEAD (pu), Speed Dead Band	
	KSTAT (pu), Speed Gain	
	KHP (pu), High Pressure Constant	
	TC (sec), Measuring transducer time constant	
	T 1 (sec), Regulator Integrator Time Constant	
	TEHP (sec), Hydro Converter Time Constant	
	TV > 0 (sec), Regulation Valve Time Constant	
	THP (sec), High Pressure Time Constant	
	TR (sec), Reheater time constant	
	TW (sec), Water Time Constant	
	NTMAX (pu), Power Regulator-Integrator Maximum Limiter	
	NTMIN (pu), Power Regulator-Integrator Minimum Limiter	
	GMAX (pu), Valve Maximum Open	
	GMIN (pu), Valve Minimum Open	
	VMIN (pu/sec), Valve Maximum Speed Close	
	VMAX (pu/sec), Valve Maximum Speed Open	

Commonly Used Steam Turbine Generic Models Block Diagrams:

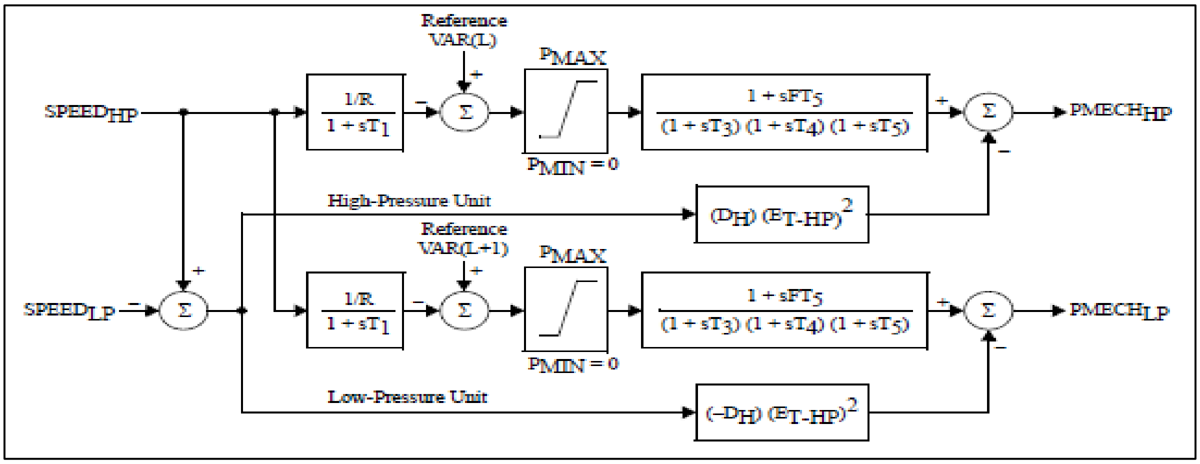
- **BBGOV1: Brown-Boveri turbine-governor model**



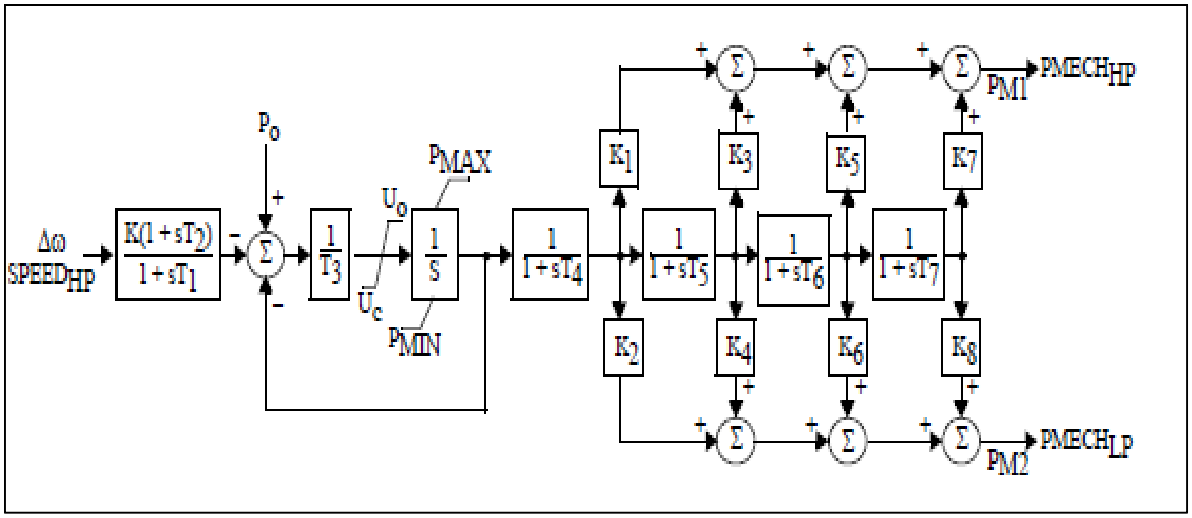
- **TGOV1: Steam turbine-governor model**



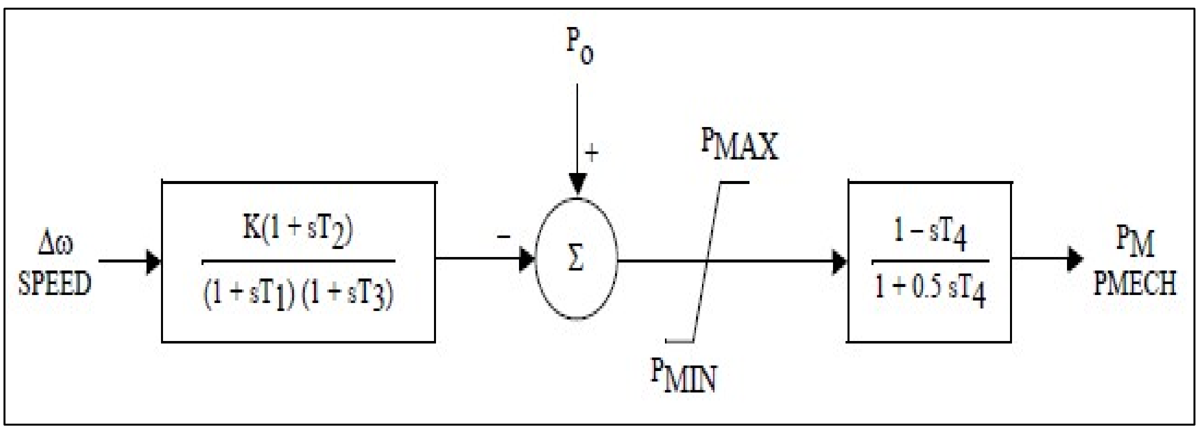
- **CRCMGV: Cross compound turbine-governor model**



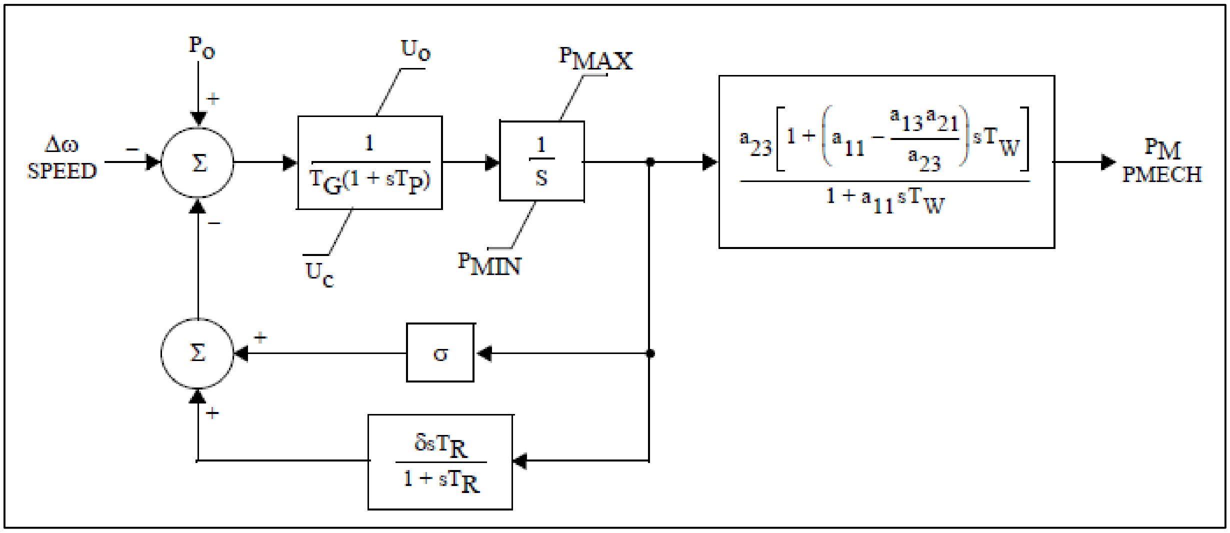
- **IEEEG1: 1981 IEEE type 1 turbine-governor model**



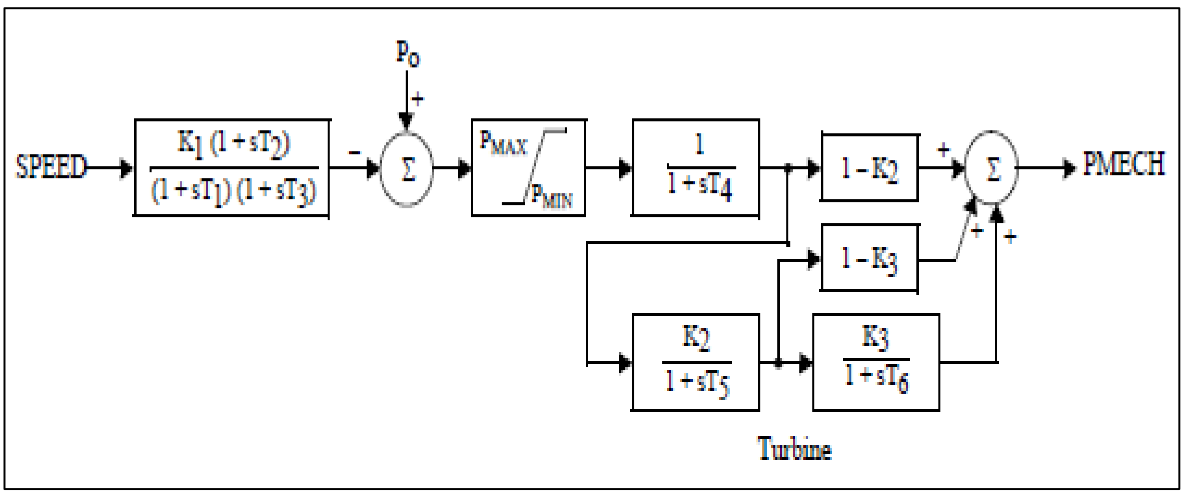
- **IEEEG2: 1981 IEEE Type 2 Speed-Governing Model**



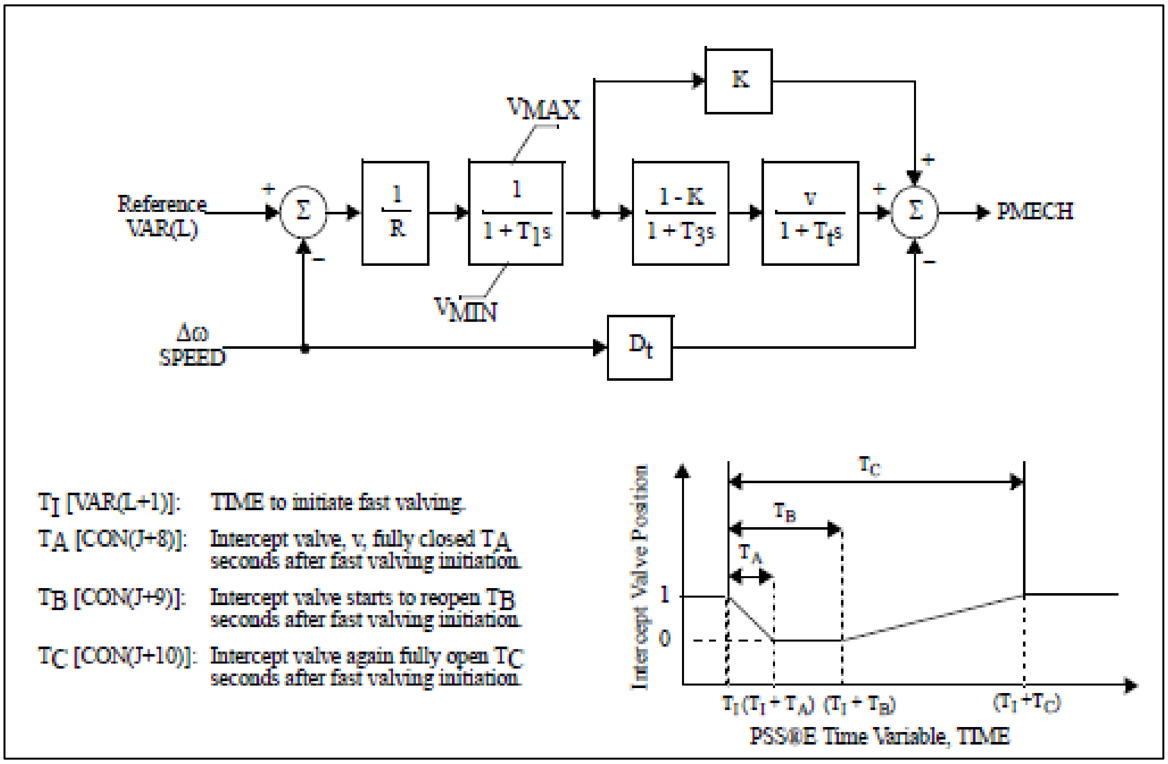
- **IEEEG3: 1981 IEEE Type 3 Speed-Governing Model**



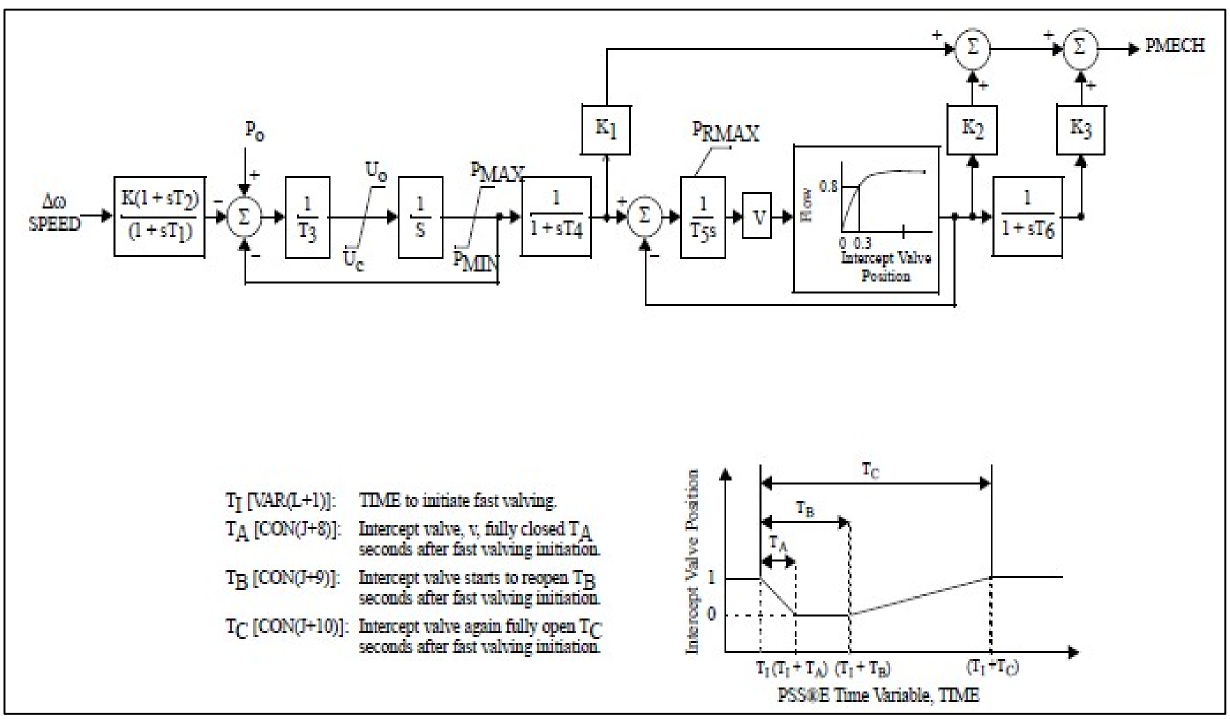
- **IEESGO: 1973 IEEE standard turbine-governor model**



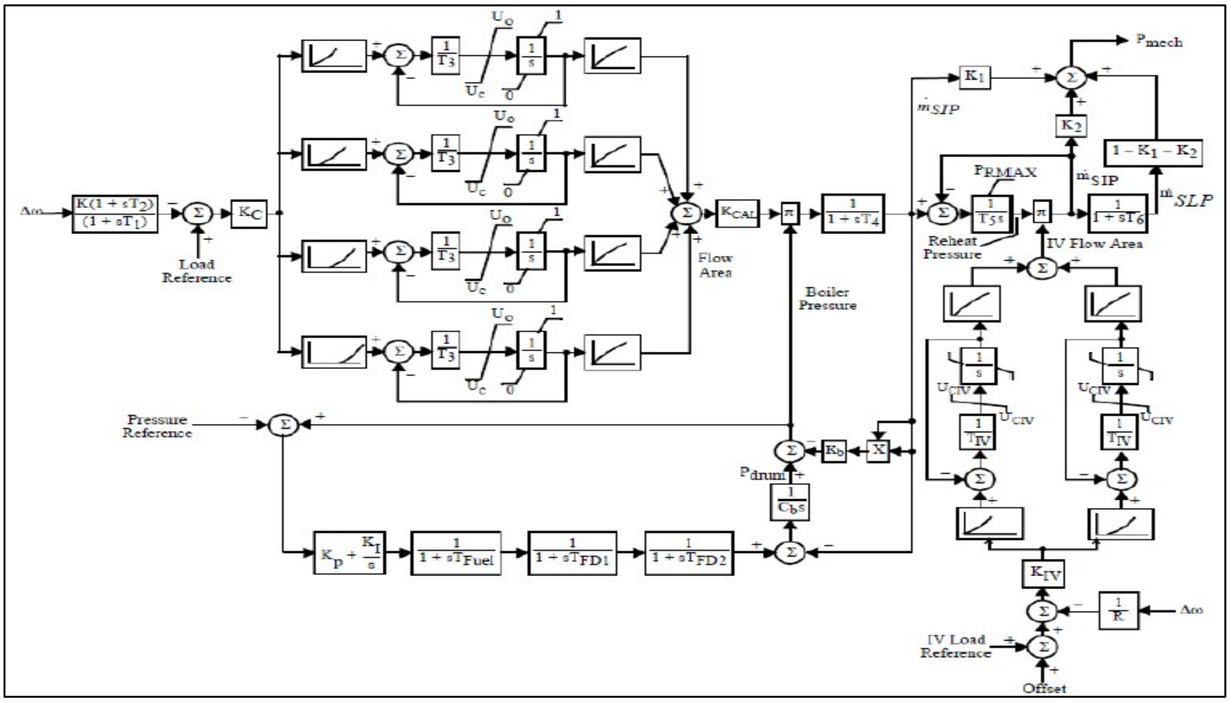
- **TGOV2: Steam turbine-governor model with fast valving**



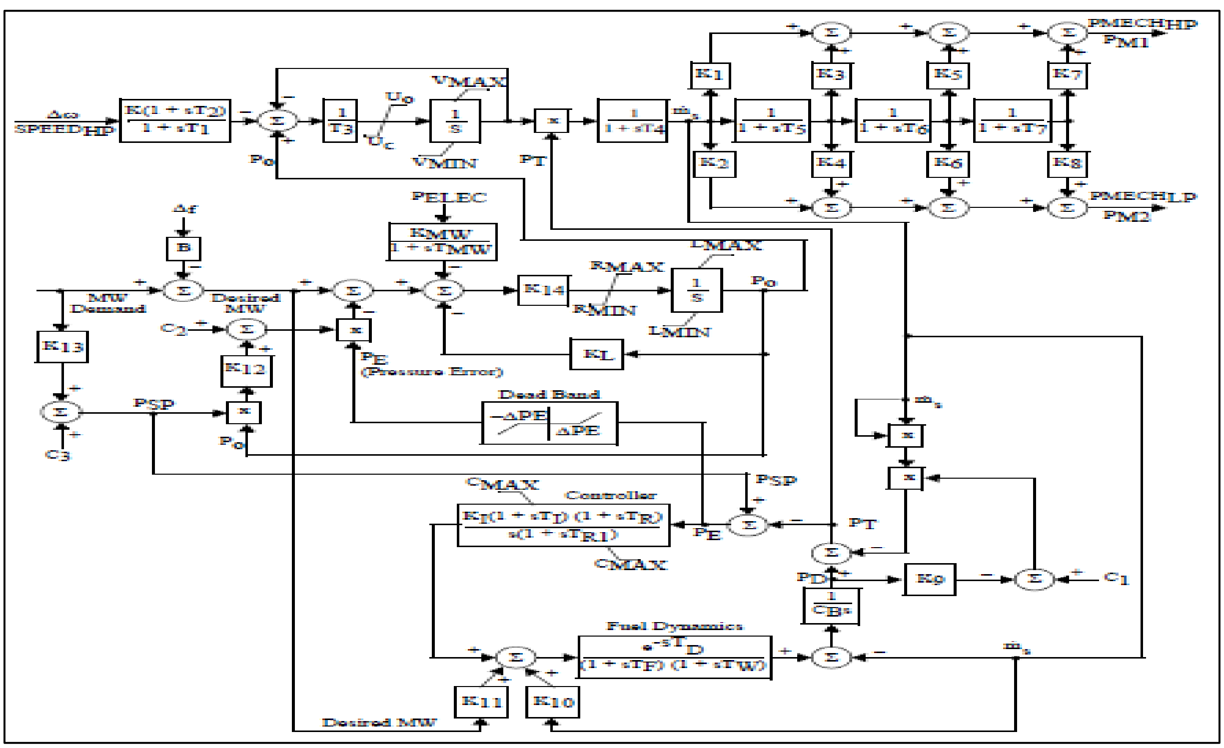
- **TGOV3: Modified IEEE type 1 turbine-governor model with fast valving**



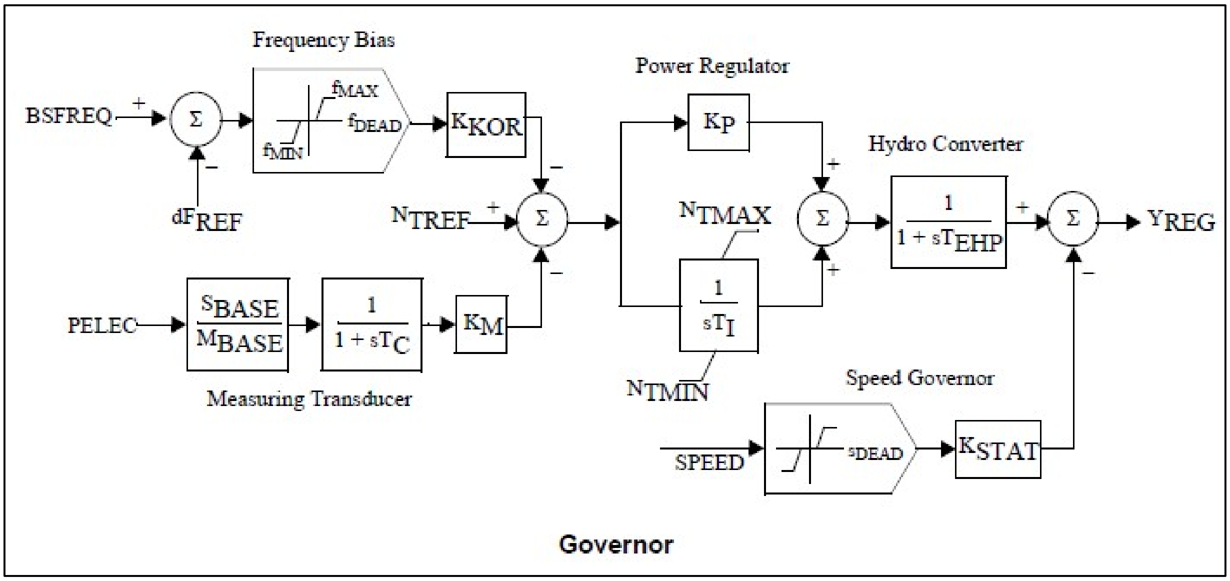
➢ **TGOV4: Modified IEEE type 1 speed governing model with PLU and EVA**

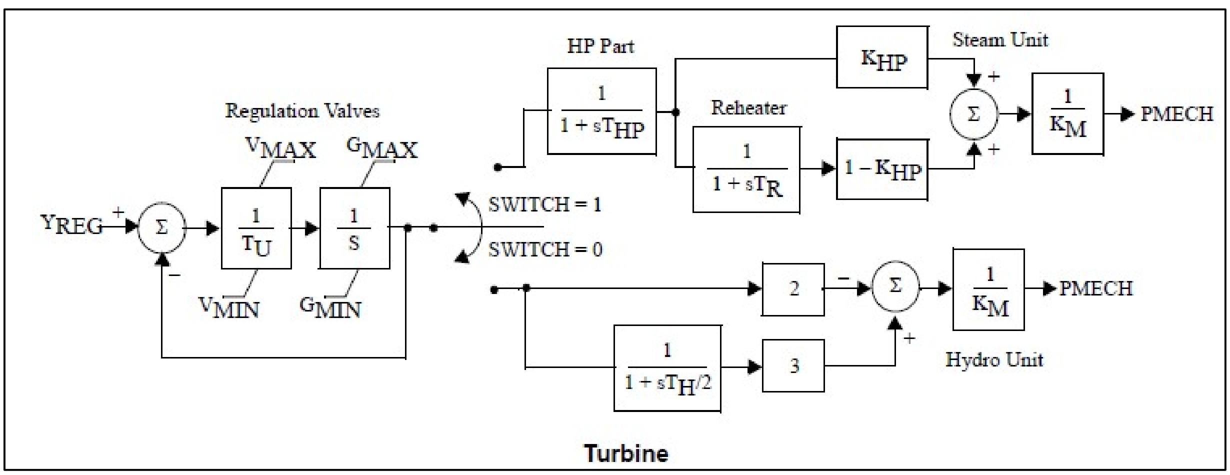


➢ **TGOV5: Modified IEEE type 1 turbine-governor model with boiler controls**



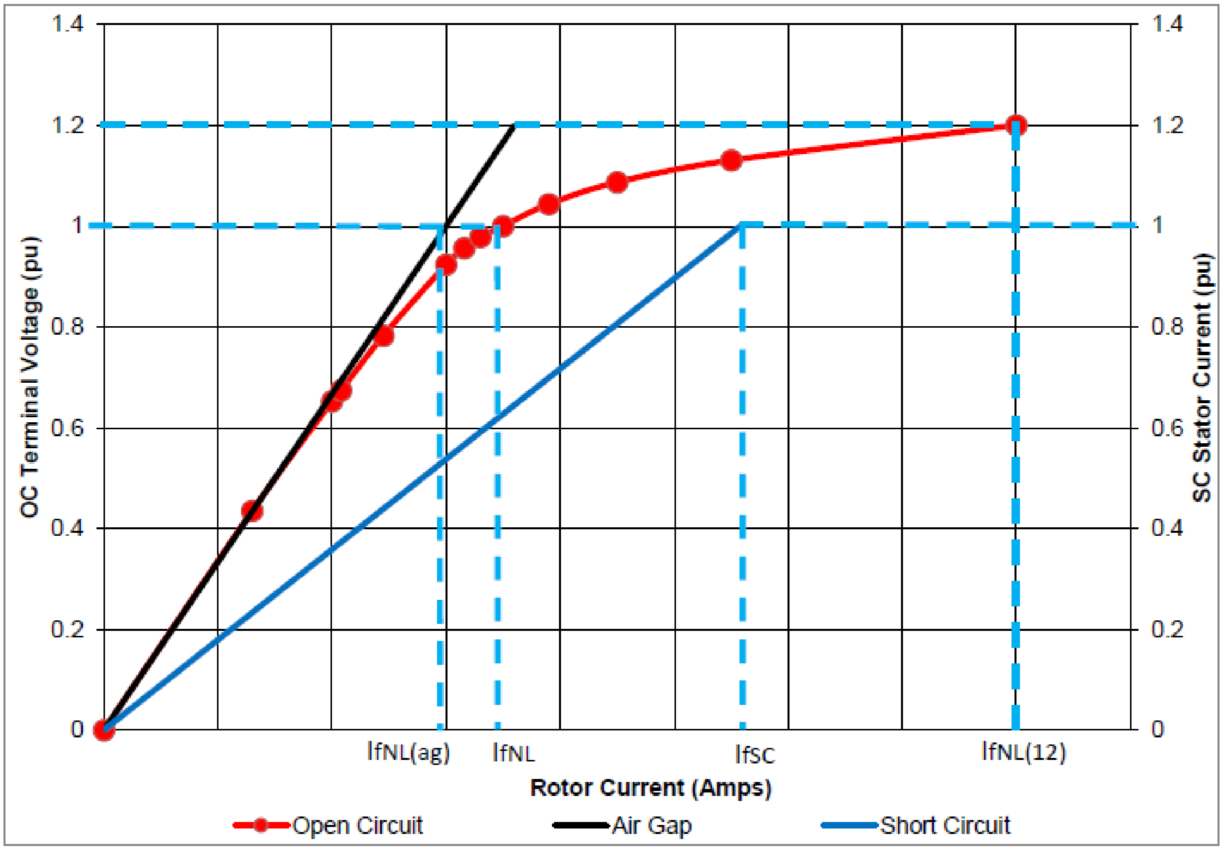
- **TURCZT: Czech Hydro and Steam Governor**





Source-PSSE Model Library

Calculation of saturation parameters:



Open and short circuit characteristics

The saturation can be calculated using the following calculation:

$$S(1.0) = \frac{If_{NL} - If_{NL(AG)}}{If_{NL(AG)}}$$

$$S(1.2) = \frac{If_{NL(12)} - 1.2 \times If_{NL(AG)}}{1.2 \times If_{NL(AG)}}$$